ATV12P075M2

variable speed drive ATV12 - 0.75kW - 1hp - 200..240V - 1ph - on base plate



Main Range of product Altivar 12 Product or component Variable speed drive type Product specific Simple machine application Mounting mode Cabinet mount Communication port Modbus protocol 50/60 Hz +/- 5 % Supply frequency [Us] rated supply 200...240 V - 15...10 % voltage Nominal output current 4.2 A Motor power hp 1 hp 0.75 kW Motor power kW Motor power hp 1 hp EMC filter Integrated IP20 IP degree of protection

Complementary

Complementary		
Discrete input number	4	
Discrete output number	2	
Analogue input number	1	
Analogue output number	1	
Relay output number	1	
Physical interface	2-wire RS 485	
Connector type	1 RJ45	
Continuous output current	4.2 A at 4 kHz	
Method of access	Server Modbus serial	
Speed drive output frequency	0.5400 Hz	
Speed range	120	
Sampling duration	20 Ms, tolerance +/- 1 ms for logic input 10 ms for analogue input	
Linearity error	+/- 0.3 % of maximum value for analogue input	
Frequency resolution	Analog input: converter A/D, 10 bits Display unit: 0.1 Hz	
Time constant	20 ms +/- 1 ms for reference change	
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s	
Transmission frame	RTU	
Number of addresses	1247	
Data format	8 bits, configurable odd, even or no parity	
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/Write multiple registers (23) 4/4 words Read device identification (43)	
Type of polarization	No impedance	
4 quadrant operation possible	False	

Asynchronous motor control profile	Sensorless flux vector control Voltage/Frequency ratio (V/f) Quadratic voltage/frequency ratio	
Maximum output frequency	4 kHz	
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor	
Acceleration and deceleration ramps	S U Linear from 0 to 999.9 s	
Motor slip compensation	Preset in factory Adjustable	
Switching frequency	216 kHz adjustable 416 kHz with derating factor	
Nominal switching frequency	4 kHz	
Braking to standstill	By DC injection	
Brake chopper integrated	False	
Line current	10.2 A at 100 V (heavy duty) 8.5 A at 120 V (heavy duty)	
Maximum input current	8.5 A	
Maximum output voltage	240 V	
Apparent power	2.0 kVA at 240 V (heavy duty)	
Maximum transient current	6.3 A during 60 s (heavy duty) 6.9 A during 2 s (heavy duty)	
Network frequency	5060 Hz	
Relative symmetric network frequency tolerance	5 %	
Prospective line Isc	1 kA	
Base load current at high overload	4.2 A	
Power dissipation in W	Natural: 44.0 W	
With safety function Safely Limited Speed (SLS)	False	
With safety function Safe brake management (SBC/SBT)	False	
With safety function Safe Operating Stop (SOS)	False	
With safety function Safe Position (SP)	False	
With safety function Safe programmable logic	False	
With safety function Safe Speed Monitor (SSM)	False	
With safety function Safe Stop 1 (SS1)	False	
With sft fct Safe Stop 2 (SS2)	False	
With safety function Safe torque off (STO)	False	
With safety function Safely Limited Position (SLP)	False	
With safety function Safe Direction (SDI)	False	
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I²t	
Tightening torque	0.8 N.m	
Insulation	Electrical between power and control	
Quantity per set	Set of 1	
Width	72 mm	
Height	143 mm	
Depth	102.2 mm	
Net weight	0.7 kg	

Environment

Environment		
Operating altitude	> 10002000 m with current derating 1 % per 100 m <= 1000 m without derating	
Operating position	Vertical +/- 10 degree	
Product certifications	NOM CSA C-Tick UL GOST RCM KC	
Marking	CE	
Standards	UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3	
Assembly style	On base plate	
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11	
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3	
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms	
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz	
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz	
Overvoltage category	Class III	
Regulation loop	Adjustable PID regulator	
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 212 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2, 4 and 16 kHz shielded motor cable <10 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m	
Vibration resistance	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6	
Shock resistance	15 gn conforming to EN/IEC 60068-2-27 for 11 ms	
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3	
Noise level	0 dB	
Pollution degree	2	
Ambient air transport temperature	-2570 °C	
Ambient air temperature for operation	-1040 °C without derating 4060 °C with current derating 2.2 % per °C	
Ambient air temperature for storage	-2570 °C	

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	12.000 cm
Package 1 Width	18.700 cm
Package 1 Length	19.500 cm
Package 1 Weight	974.000 g
Unit Type of Package 2	P06
Number of Units in Package 2	45
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	56.155 kg

Offer Sustainability

☑ REACh Declaration	
Pro-active compliance (Product out of EU RoHS legal scope)	
Yes	
☑ China RoHS Declaration	
₫Yes	
The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	

Contractual warranty

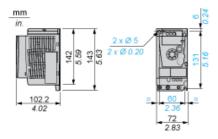
Warranty	18 months	

Product data sheet Dimensions Drawings

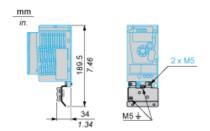
ATV12P075M2

Dimensions

Drive without EMC Conformity Kit



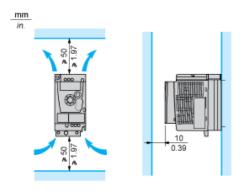
Drive with EMC Conformity Kit



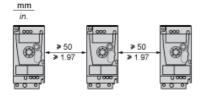
ATV12P075M2

Mounting Recommendations

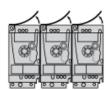
Clearance for Vertical Mounting



Mounting Type A

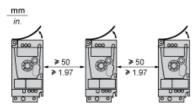


Mounting Type B



Remove the protective cover from the top of the drive.

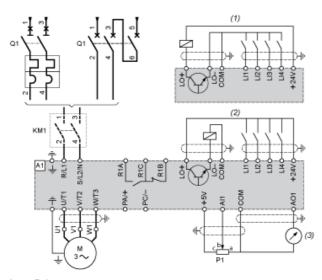
Mounting Type C



Remove the protective cover from the top of the drive.

ATV12P075M2

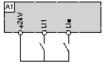
Single-Phase Power Supply Wiring Diagram



- A1 Drive
- KM1 Contactor (only if a control circuit is needed)
- P1 2.2 k Ω reference potentiometer. This can be replaced by a 10 k Ω potentiometer (maximum).
- Q1 Circuit breaker
- (1) Negative logic (Sink)
- (2) Positive logic (Source) (factory set configuration)
- (3) 0...10 V or 0...20 mA

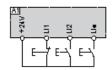
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



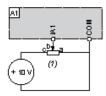
LI1 : Forward LI• : Reverse A1 : Drive

3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive

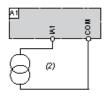
Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 $k\Omega$...10 $k\Omega$ reference potentiometer

A1: Drive

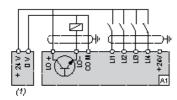
Analog Input Configured for Current with Internal Power Supply



0-20 mA 4-20 mA supply

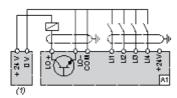
À1: Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vd A1: Drive 24 vdc supply

Connected as Negative Logic (Sink) with External 24 vdc supply



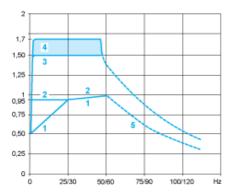
(1) 24 vdc supply

A1: Drive

Product data sheet Performance Curves

ATV12P075M2

Torque Curves



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.