

# AI-based defect detection that exceeds the ability of expert inspectors





# A better option for inspections requiring specialist knowledge and high sensitivity

### Meeting sensory inspection needs amid a shortage of skilled inspectors

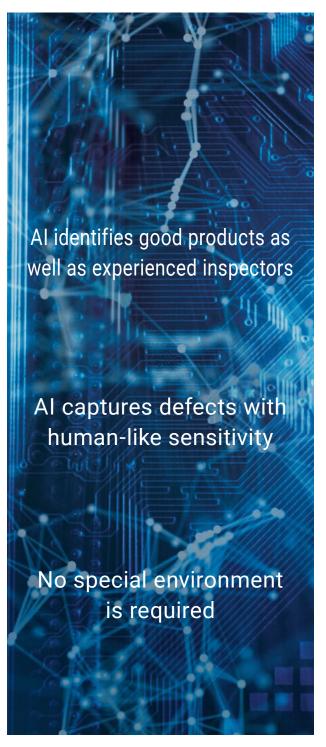
Skilled inspectors are hard to come by these days, and labor costs have risen sharply. Manufacturers are now facing intense pressure to automate processes that rely on the senses of experienced human workers. Particularly when it comes to visual inspection, it's important to reliably identify subtle defects even on flexible lines producing a wide range of items. Traditionally, the knowledge and sensitivity of technicians with long-term experience has been key. However, artificial intelligence is now reaching the stage where it can recognize object features as well as humans and automatically learn criteria. While a lot of Al solutions faces challenges with large amounts of image data, specialized hardware and engineering expertise, Omron is making great progress in enabling its widespread use.



# Al reproduces human experience and sensibility

To solve these challenges, Omron developed new defect detection AI that reproduces the techniques of skilled inspectors. This AI is now part of the FH Vision System.





# Al identifies good products as well as experienced inspectors

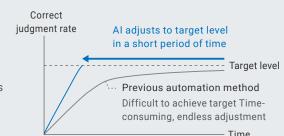
Sensory inspection requires a certain tolerance for variations that don't pass a certain threshold. Determining what variations are acceptable is a key capability of expert inspectors and poses a challenge for automated inspection systems.



The FH Series can determine acceptable variation tolerances.

#### **Al Fine Matching**

Omron's AI Fine Matching tool learns from the image data of non-defective products to quickly acquire the "expertise" that inspectors develop over the course of many years. This reduces costs and boosts productivity through automation.



Judges as non-defective product

- Time Target inspection level: Reduce overdetection Difference image Al automation method Previous automation method Contamination inspection Detects position differences, not Detects foreign materials only foreign materials, as defects and ignores position differences of LED modules Captured image Defective product With foreign materials Overdetection Detects foreign material only Non-defective product Position difference of die Overdetection Judges as non-defective product Non-defective product Position difference and light variation of surrounding part

Overdetection

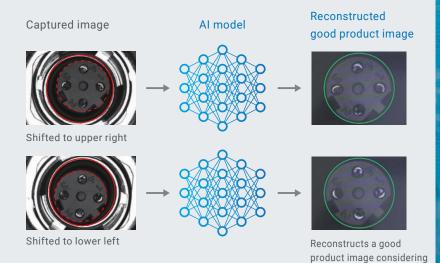
# Al Fine Matching

### Al reduces overdetection

Al Fine Matching identifies a future that is not included in good products as a defect.

Al learns images of good products with variations, and generates an AI model.

Every time an inspection is carried out, Al reconstructs a model that is presumed to be a good product. Al extracts a difference between the reconstructed good product image and a captured image to identify a defect, reducing overdetection.



# Al makes it easy to avoid overdetection PATENT PENDING

Three quick steps on the settings screen guide the user through the process of creating the good product model with the minimum number of images.

### Prepare images

Although standard Al processing requires a huge number of images for learning, the FH Series requires only 100 to 200 images.

Good product image



Defective product image



### 2 Create model

The system suggests images to learn, helping to complete the good product model.

Al makes it easy



Al model

#### 3 Check results

Test is automatically performed using images prepared in Step 1. You don't need to adjust parameters for differential inspections.

different views of holes

#### Al makes it easy



Correlation score Image A:10 Image B:150

When a good product is judged as defective, Al gives each image a correlation score to visualize the degree of overdetection. This facilitates selecting images that need to be learned to reduce overdetection.

<sup>\*1. &</sup>quot;Patent pending" means that we applied for a patent in Japan, and "Patented" means that we obtained a patent in Japan. (as of May 2022)

# Al captures defects with human-like sensitivity

Defect detection tasks that rely on human sensibility are a challenge to automate. Fortunately, powerful new Al technology can match the skills and capabilities of experienced inspectors.



Automating human vision-based inspection with the FH Series

#### **AI Scratch Detect Filter**

The latest capabilities of the FH Vision System include a new Al-based image filter that reproduces the technique that skilled inspectors use to identify a defect on any product background. Scratches and blemishes that were once difficult to capture can now be identified even without the use of samples or adjustment.



Captured image



Previous detection image
Cannot separate a scratch from noise



Detection image
Can detect a scratch only



\*1. The FH-UMAI1 Scratch Detect Al Software Installer is required to use Al Scratch Detect Filter.

# Al Scratch Detect Filter

Al reproduces human expertise through learned criteria

The AI Scratch Defect Filter learns by means of images in which human inspectors noticed defects. Whereas previous inspection methods found the unexpected size, shape or color of a particular defect to be a barrier to automation, AI successfully extracts abnormalities by judging their features without definition. The learned data facilitates defect detection on processed surfaces and other uneven backgrounds that previously posed an insurmountable challenge.

Captured image



Extracted scratch (internal image)



# Solutions using Al



#### Al identifies good products as well as experienced inspectors

- Uneven colors and dimensional variations within tolerance
- · Difficult to identify defects due to complex shapes
- Time-consuming inspection area setting and parameter adjustment for different shapes of many objects

#### **Al Fine Matching**

- · Reliable detection by learning variations in colors and dimensions of good products
- · Identification of defects in complex-shaped parts
- · Quick setting for many objects with different shapes by simply enclosing inspection areas

#### Print inspection for product labels

Variations in darkness, thickness, and positions of printed characters are acceptable, and only defects such as chipped characters are detected. The inspection area is set to the entire label.









Chipped character

Ink splatter

Chip and contamination inspection for electronic parts

Minor dimensional differences are permitted, and only defects are detected in complex-shaped parts. The inspection area is set to the entire part surface.











Chipped resin

Foreign material

Contamination and shape inspection for resin molded parts

Efficient learning of many objects with different shapes enables quick setting of conditions for extracting only defects from complex shapes. The inspection area is set according to the shape of the molded part.











Shape A: foreign material

Shape B: foreign material and deformation

#### Al captures defects with human-like sensitivity

#### Issue

- · Filters and parameters are combined and adjusted to detect low-contrast defects.
- · Low-contrast defects cannot be detected.

#### Al Scratch Detect Filter

· Regardless of material type, color, or size, defects can be extracted reliably without previously required definition and adjustment.





Scratch on sandblasted metal



Black scratch on hairline finish



Scratch on resin products





White scratch on shaded hairline finish

# No special environment is required

With the FH Series, there's no need for high-end hardware or specialized engineers who can configure the system to suit your needs. Our general-purpose vision system makes it easier than ever to introduce Al into production sites.

### Vision controller with AI functionality

Artificial intelligence has traditionally required a high-end environment, but our lightweight creative solution comes in the form of user-friendly processing items that have been integrated into our popular FH Series hardware.

# No special hardware for Al required

It used to be difficult to introduce AI technology to many inspection processes because of its hardware requirements. The FH Series does not require special hardware, facilitating the introduction of this technology. The FH Series does not require special hardware, facilitating introduction.

#### No AI engineer required

In order to reliably use AI technology in processes, the engineer used to have not only image processing skills but also programming and maintenance skills. With the FH Series, however, you can use AI technology just like operating a standard vision sensor. No dedicated AI engineer is required.



Intel® Core™ i7 processor



Outstanding processing speed

Ultra-high-speed CPU RAM

4 times faster\*1 than our previous models

Outstanding processing speed

Large-capacity RAM

To times larger\*1 than our previous models

Machine control network
 Cycle: 125 μs



2 Data output High-speed interface: USB 3.0

<sup>\*1.</sup> The FH-5550 Controller is compared with the FH-3050 Controller.

### High-resolution cameras

We offer a range of cameras that can capture high-resolution images suitable for sensory inspection at high speeds.



# Ultra-high-speed sensing technology in a compact design

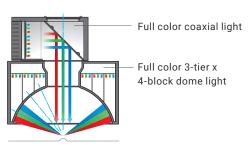
There was a trade-off between high-resolution image capture like the human eye and inspection processing speed. We use new CMOS image elements and dual transfer technology to capture high-resolution images while transferring images at high speeds. This facilitates applications that previously required multiple cameras or a mechanism to move a camera.

# MDMC light with flexible lighting patterns

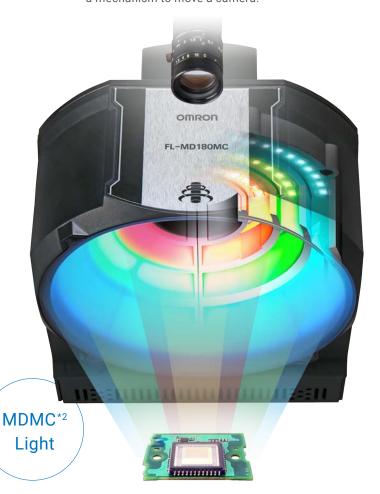
This light can be adjusted to defects by combining the illumination colors and angles like humans do. Even if new objects or inspection items are added after installation, there is no need to add or change the light—just change the illumination pattern. The illumination patterns can be registered as settings, facilitating duplicating production lines.

#### Illumination structure

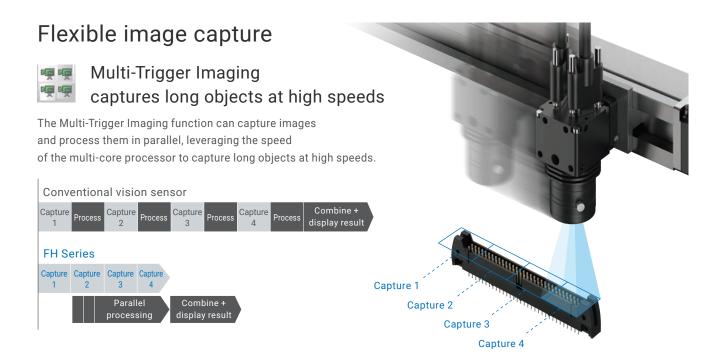
You can choose the best pattern by combining illumination directions x full color RGB x 128 brightness levels of 13 blocks.







# Software for flexible automation

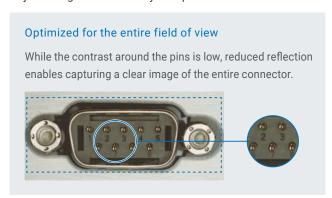


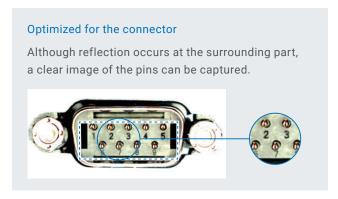


#### Camera Image Input HDR optimizes contrast

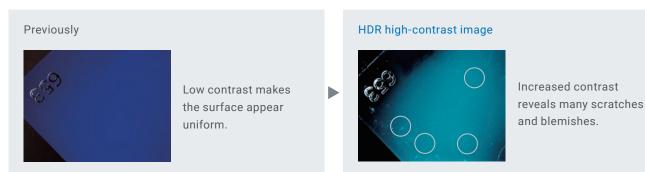
Camera Image Input HDR helps create optimized HDR images under variable ambient conditions. Once you specify the optimum area to capture on the image, the FH Series automatically adjusts the shutter speed while capturing images and combining the images.

#### Adjusts brightness to suit your specified area





#### Detects low-contrast defects in high-contrast mode



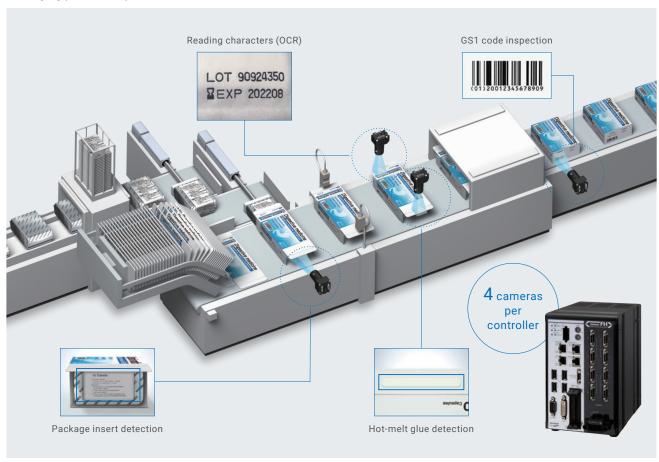
# Parallel processing for different inspections

#### Multi-Line Random-Trigger inspects at up to four different timings

A single controller can perform inspections at different points at different timings.

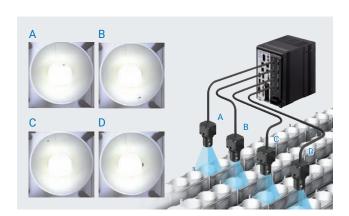
Controllers installed for each process can be integrated into one, reducing initial costs and saving space.

#### Packaging process of pharmaceuticals



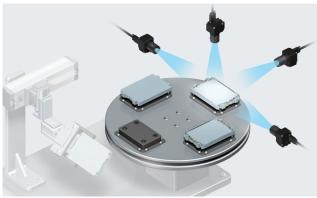
#### Contamination inspection of beverage containers

A single controller that can control each line saves initial costs and space.



#### Appearance inspection of rechargeable battery cells

Four cameras can be connected to one controller, enabling simultaneous inspection of dents and scratches from four directions.

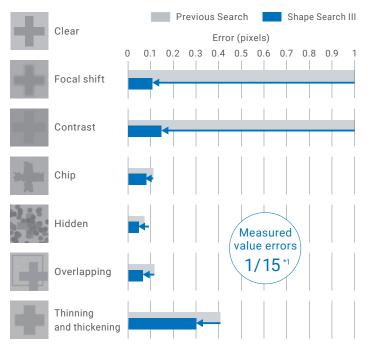


### High-speed, high-precision positioning

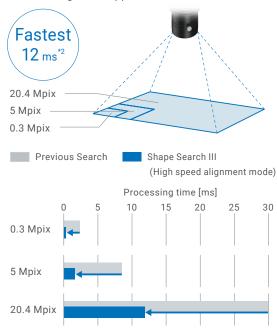


#### Shape Search III is robust against shape variations

High-precision and robust positioning is possible even under the adverse conditions, such as changes in environments and materials.



A 20.4 Mpix camera can search a positioning mark in as fast as 12 ms\*2, and a 5 Mpix camera, widely used for alignment applications, in as fast as 2 ms.

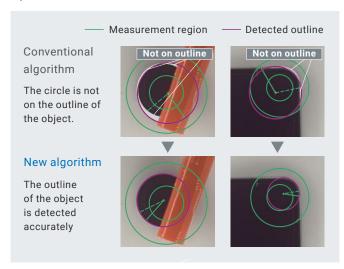


\*1. The value measured under our specified conditions is provided for reference. \*2. The value measured under our specified conditions is provided for reference. 20.4 Mpix camera.



# Circular Scan Edge Position accurately estimates the center and radius of a circle

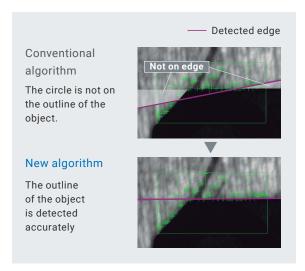
The new algorithm accurately detects a whole circle from a part of the circle.





# Scan Edge Position removes noise to detect edges

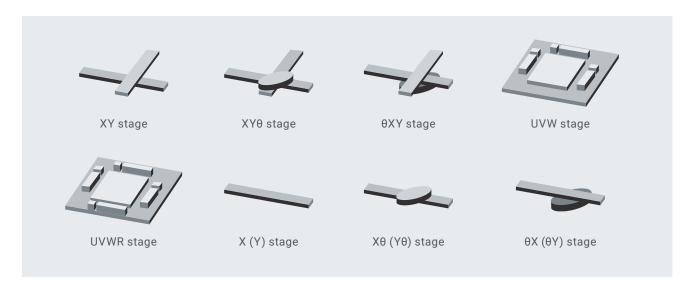
This algorithm accurately estimates lines even when the edges are unclear due to variations in objects or disturbance.





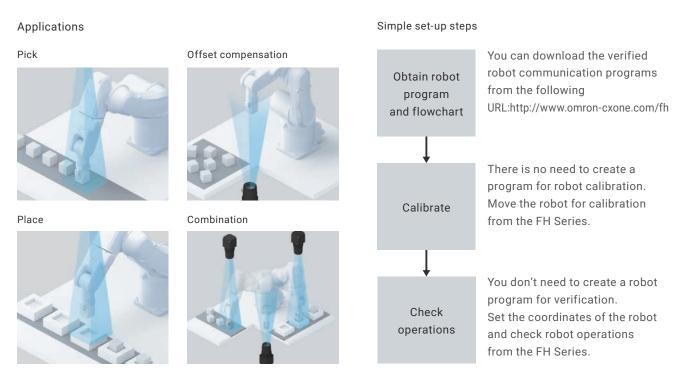
#### Stage Data calculates for various stages

The popular single axis  $+ \theta$  axis stages as well as UVW stages can be used. The use of the same axis for both handling and positioning simplifies machine configuration.



#### Robot Setting Tool simplifies connecting robots

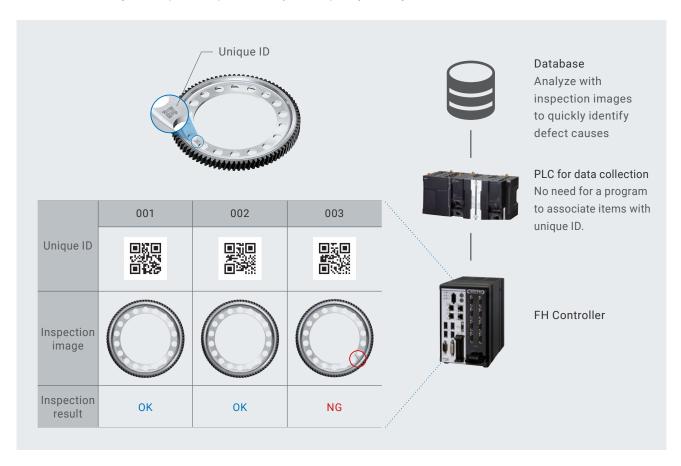
Communication programs to connect robots from various vendors and FH flowcharts required for robot applications are provided free of charge. You can quickly set up robot vision applications.



### Unique identification and quality control

#### Unique ID associated with inspection image and result

The FH Series can associate a unique ID with the inspection image and result, and then output them to the host device. You can immediately find required inspection images and quickly identify causes of fails.



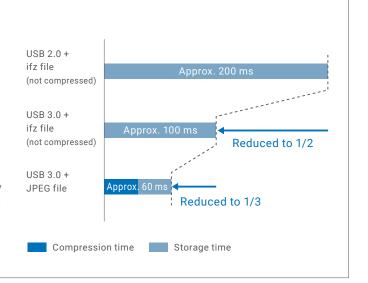
# High-speed image storage The amount of inspection image data required

for defect cause analysis can be so large that conventional controllers are unable to store it given their storage time and capacity constraints.

The high-speed, large-capacity controller has USB 3.0 ports and the improved algorithm to compress image data at high speeds, enabling all images to be stored to meet increasing needs in quality control.

The times in the right figure provided for reference only and their accuracy cannot be guaranteed. They are measured under the following conditions:

- •FH-5050 Controller
- •5 Mpix monochrome images
- •Size of converted JPEG file: 0.6 MB



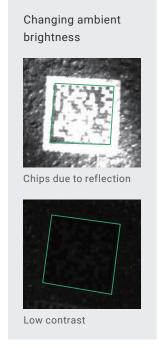


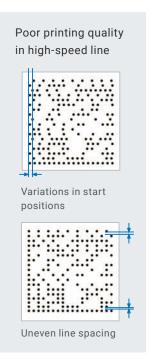
#### 2D Code II provides powerful code reading

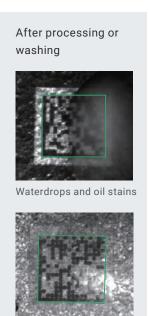
Recognition rate 2 times\*1

 $3_{\text{times}} \\ \text{faster}^{^{\star 1}}$ 

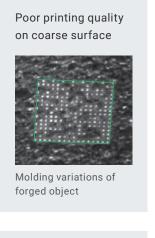
The FH Series incorporates a dedicated algorithm for reliable and fast 2D code reading even under variable ambient brightness or adverse conditions such as after processing or washing.







Scratched damage



#### Print Quality Grading Function

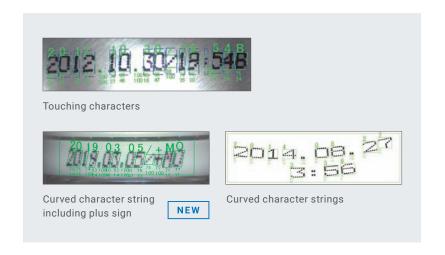
- · ISO/IEC 15415
- · ISO/IEC TR29158





# OCR reliably reads difficult-to-read characters

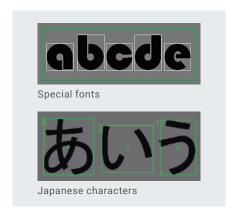
OCR can reliably read characters printed too close to each other or on curved surfaces. Also plus signs can be read.





# Character Inspection reads special fonts

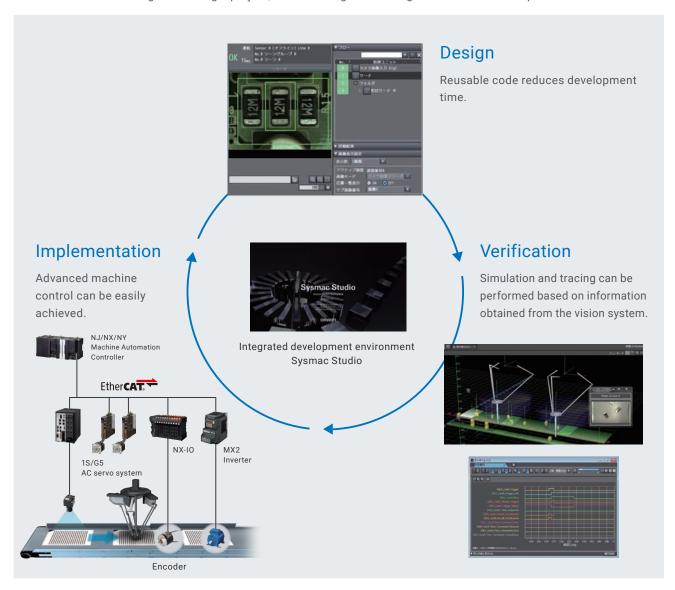
Character Inspection recognizes special fonts and non-alphanumeric characters based on pattern search using the dictionary set up by the user.

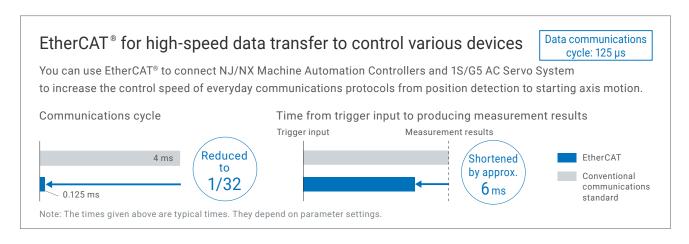


# Design interface for quick setup

### Integrated development environment Sysmac Studio

Sysmac Studio is a unique environment that integrates logic, motion and drives, robotics, safety, visualization, and information technologies in a single project, thus reducing the learning curve and the intra-operative software costs.





# Total Design Management Editor simplifies complex processing design

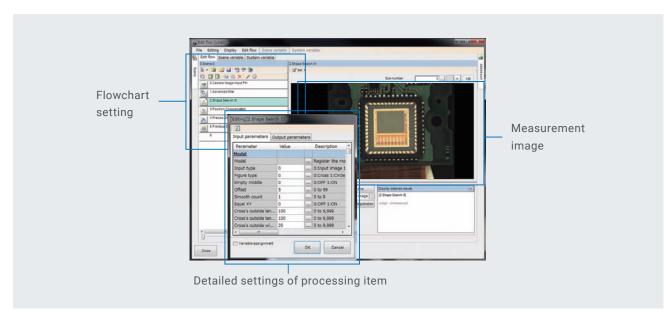
This design interface includes pre-installed screens for all phases, from design through to setting and operation. Just select processing items and determine the order to manage variables. Time-consuming calculations and inputs are no longer required.

#### Easy setting

All the common settings of multiple scenes can be made at once. Simplified inspection flowcharts reduce setting errors and prevent from forgetting to change settings.

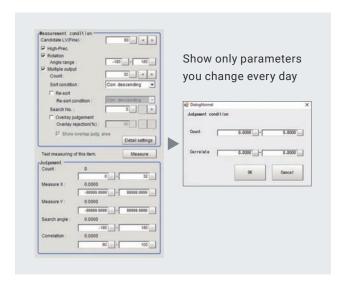
#### Efficient setting

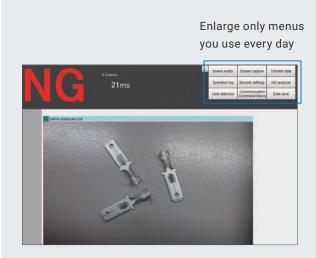
To inspect aligned parts, the FH Series can repeat the same measurements while shifting the measurement region within the same image. This reduces setting times.



# Customizable user interface simplifies operations at production sites

Showing only necessary screens for production makes the interface easier to use. Screen layout can be customized just by selecting and placing objects, without programming.





# **Vision System**

# **FH-Series**

### Al-based automated visual inspection

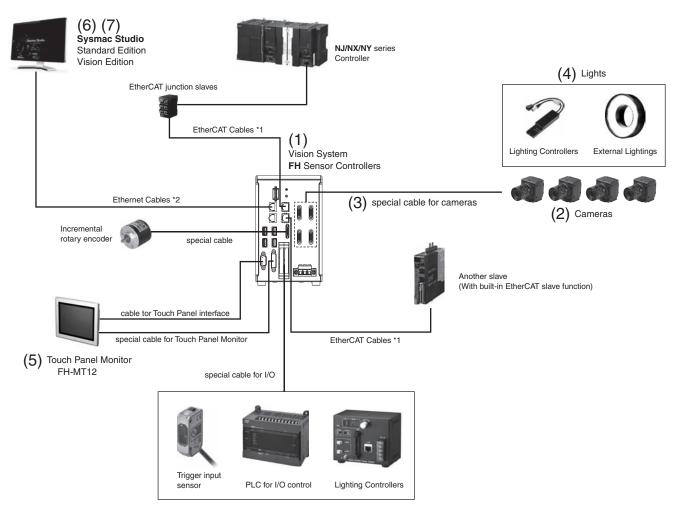
- Al reproduces human sensibility and experience
- Software for flexible automation
- · Design interface for quick setup



#### **System configuration**

#### **EtherCAT connections for FH series**

Example of the FH Sensor Controllers (4-camera type)



<sup>\*1.</sup> To use STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT and RJ45 connector.

<sup>\*2.</sup> To use STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.



#### (1) Controllers

Select a controller based on the required processing speed and network.

	Series	CPU	Performance	Memory	No. of connectable cameras	Fieldbus
High-speed, Large-capacity Controller	FH-5550 Series	Intel <sup>®</sup> Core™ i7 processor 4 cores	****	RAM 32 GB, ROM 64 GB	8 max.	PROFINET, EtherNet/IP®, EtherCAT
High-speed Controller	FH-5050 Series	Intel <sup>®</sup> Core <sup>™</sup> i7 processor 4 cores	****	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP®, EtherCAT
Standard Controller	FH-2050 Series	Intel® Celeron® processor 2 cores	***	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP®, EtherCAT
Lite Controller	FH-L551 Series	Intel® Atom® processor 2 cores	*	RAM 4 GB, ROM 32 GB	4 max.	PROFINET, EtherNet/IP®

Optional product (sold separately) Model

Scratch Detect AI Software Installer\* FH-UMAI1

#### (2) Cameras

Choose the right camera to suit your required number of pixels. Easy-to-use cameras with built-in light are also available.



No. of pixels	High-speed camera	Standard camera	Rolling shutter camera	Camera with built-in light
20.4 Mpix*			FH-S□21R	
12 Mpix	FH-S□X12			
5 Mpix	FH-S□X05	FZ-S□5M3	FH-S□05R	
2 Mpix	FH-S□02	FZ-S□2M		
0.4 Mpix/0.3 Mpix	FH-S□X	FZ-S□		FZ-SQ

<sup>\* 20.4</sup> Mpix Cameras can be used with the FH-5050/2050-series High-speed, Large-capacity Controllers.

#### (4) Lights

Omron offers a complete line-up of lights required for image processing. The use of the camera-mount lighting controller allows you to control lighting conditions from the FH Controller, making system configuration simple.



#### **External lighting controller**

Description	LED	High-brightness LED
Camera-mount Lighting Controller	FLV-TCC	FL-TCC
Bar Light	FLV-BR	FL-BR
Direct Ring Light	FLV-DR	FL-DR
Low Angle Ring Light	FLV-DL	
Coaxial Light	FLV-CL	
Shadowless Light	FLV-FR/FP/FS/FQ	
Spot Light	FLV-EP	
Direct Back/Edge Type Light	FLV-DB/FB	
Dome Light	FLV-DD	
Photometric Stereo Light *		FL-PS

<sup>\*</sup> The FL-TCC Camera-mount Lighting Controller cannot be used. Use the FL-TCC1PS Lighting Controller for Photometric Stereo Light.

#### **Built-in lighting controller**

Description	Model
MDMC Light	FL-MD

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

#### (5) Touch panel monitor

The touch panel monitor is optimized for the operation of the FH Series.



Description	Model
Touch Panel Monitor 12.1 inches	FH-MT12
DVI-Analog Conversion Cable for Touch Panel Monitor	FH-VMDA □□
USB Cable for Touch Panel Monitor	FH-VUAB □□

<sup>\*</sup> RS-232C cables for long-distance connections are also available. Refer to Ordering Information for details.

#### (3) Camera cables

The cable line-up includes bend-resistant cables and right-angle cables. Use the FZ-VSJ Cable Extension Unit for cable extensions.



★: The more stars, the higher the performance.

Description	Model
Camera Cable	FZ-VS□ □□M
Bend-resistant Camera Cable	FZ-VSB3 □□M
Super-bend-resistant Camera Cable	FZ-VSBX □□M
Right-angle Camera Cable	FZ-VSL□ □□M
Bend-resistant Right-angle Camera Cable	FZ-VSLB3 □□M
Cable Extension Unit	FZ-VSJ

#### (6) Sysmac Studio

The development environment for the Sysmac platform allows you to configure and simulate the FH Series on your PC.



Description	Model		
DVD for installation	SYSMAC-SE200D		
Software license (Vision Edition)	SYSMAC-VE001L		

#### (7) Application producer

This development environment enables you to customize FH functions. It includes sample codes and wizards that will help you develop your own interfaces and processing items.

Description	Model
DVD for installation	FH-AP1
Software license	FH-AP1L

<sup>\*</sup> This product can be installed on the FH-5□50-series Controller (version 6.40 or later).

#### **FH-Series**

### **Ordering Information**

#### **FH Series Sensor Controllers**

			Al function		No. of			
ltem		CPU	Al Scratch Detect Filter *1	Al FineMatching	cameras	Output	Model	
	High-speed,				2	NPN/PNP	FH-5550	
	Large-capacity	Intel <sup>®</sup> Core <sup>TM</sup> i7 processor 4 cores	Available	Available	4	NPN/PNP	FH-5550-10	
District Control	Controller	processor 4 cores			8	NPN/PNP	FH-5550-20	
0 4 2					2	NPN/PNP	FH-5050	
	High-speed Controller	Intel® Core <sup>TM</sup> i7 processor 4 cores	Available	Available	4	NPN/PNP	FH-5050-10	
					8	NPN/PNP	FH-5050-20	
	Standard Controller	Intel® Celeron® processor 2 cores	Not available	Available	2	NPN/PNP	FH-2050	
- Wenter					4	NPN/PNP	FH-2050-10	
					8	NPN/PNP	FH-2050-20	
	Box type controllers	Intel® Atom®		Not available	Available *2	2	NPN/PNP	FH-L551
	Box-type controllers processor 2 cores		Ivot avallable	Available 2	4	NPN/PNP	FH-L551-10	

<sup>\*1</sup> Optional FH-UMAI1 Scratch Detect AI Software Installer is required. \*2 Use in conjunction with 0.3 or 0.4 million-pixel cameras.

#### **Optional Products (Sold Separately)**

Item	Model
Scratch Detect Al Software Installer *	FH-UMAI1

 $<sup>^\</sup>star$  This product can be installed on the FH-5 $\!\Box 50\text{-series}$  Controller (version 6.40 or later).

#### **Cameras**

	Item	Lens mount	Descriptions	Color / Monochrome	Image Acquisition Time *1	Model
	Digital CMOS Cameras	0 1	20.4 million pixels	Color	40.0 +0	FH-SC21R
~	(Lens required)	C mount	(Supported controller: FH-5□50(-□)/2050(-□) Series) *2	Monochrome	42.6 ms *3	FH-SM21R
			40 '11' ' 1 +0	Color	04.0 +0	FH-SCX12
0			12 million pixels *2	Monochrome	24.9 ms *3	FH-SMX12
	High-speed Digital		5 million pixels	Color	10.3 ms *3	FH-SCX05
	CMOS Cameras	C mount	3 million pixels	Monochrome	10.51118-5	FH-SMX05
a	(Lens required)			Color		FH-SCX
			0.4 million pixels	Monochrome	1.9ms	FH-SMX
	High-speed Digital		40	Color	0.5.5	FH-SC12
	CMOS Cameras (Lens required)	M42 mount	12 million pixels *2	Monochrome	25.7 ms *3	FH-SM12
			4 mailliana missala	Color	8.5 ms *3	FH-SC04
		4 million pixels	Monochrome	0.51118 5	FH-SM04	
	High-speed Digital		2 million nivele	Color	4.6 ms *3	FH-SC02
CMOS Cameras (Lens required)	C mount	2 million pixels	Monochrome	4.01115 3	FH-SM02	
200	(Lons required)		0.0	Color	3.3 ms	FH-SC
9			0.3 million pixels	Monochrome	3.3 1115	FH-SM
			5 million missele	Color	74.7	FH-SC05R
	Digital CMOS Cameras		5 million pixels	Monochrome	71.7ms	FH-SM05R
To the same of the	(Lens required)	C mount	5	Color	00.0	FZ-SC5M3
)			5 million pixels	Monochrome	38.2 ms	FZ-S5M3
			0 1111	Color	00.0	FZ-SC2M
1	Digital CCD Cameras	0	2 million pixels	Monochrome	33.3 ms	FZ-S2M
	(Lens required)	C mount	0.2 million nivele	Color	40.5	FZ-SC
11) 12			0.3 million pixels	Monochrome	- 12.5 ms	FZ-S
			200 000 pixel flet type	Color	- 12.5 ms	FZ-SFC
11	Small Digital	Lenses for small	300,000-pixel flat type	Monochrome		FZ-SF
	CCD Cameras (Lens required)	camera required	200 000 pivel per type	Color	10 F ma	FZ-SPC
T. H.	, , ,		300,000-pixel pen type	Monochrome	12.5 ms	FZ-SP

	Item		Descriptions	Color / Monochrome	Image Acquisition Time *1	Model
1-6-		Built-in lens	Narrow view	Color	- 16.7 ms	FZ-SQ010F
	Intelligent Compact Digital CMOS Camera		Standard view	Color		FZ-SQ050F
•			Wide View (long-distance)	Color		FZ-SQ100F
			Wide View (short-distance)	Color		FZ-SQ100N

<sup>\*3</sup> Frame rate in high speed mode when the camera is connected using two camera cables. For other conditions, refer to the table on the next page.

Model		FH- SM02	FH- SC02	FH- SM04	FH- SC04	FH- SM12	FH- SC12	FH- SMX	FH- SCX	FH- SMX05	FH- SCX05	FH- SMX12	FH- SCX12	FH- SM21R	FH- SC21R	
Image Acquisition Time *4	2 Cables	High Speed Mode *6	4.6	ms	8.5	ms	25.7	' ms	-	-	10.3	3 ms	24.9	ms ms	42.6	3 ms
	*5	Standard Mode	9.7	9.7 ms		17.9 ms 51.3 ms				22.1 ms		53.5 ms		90.1	ms	
	1 Cables	High Speed Mode *6	9.2	ms	17.0	) ms	51.3	3 ms	1.9	ms	20.6	3 ms	50.0	) ms	83.3	3 ms
	1 Cables	Standard Mode	19.3	3 ms	35.8	ms	102.0	0 ms	3.8	ms	44.1	ms	106.4	4 ms	175.4	4 ms

<sup>\*4</sup> The image acquisition time does not include the image conversion processing time of the sensor controller.
\*5 Two Camera ports of the controller are used per one camera.
\*6 Up to 5 m Camera Cable length.

#### **Camera Cables**

Item	Descriptions	Model *3
0	Camera Cable Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VS3 □M
9	Bend resistant Camera Cable Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSB3 □M
9	Super Bend resistant Camera Cable Cable length: 5 m or 10 m	FZ-VSBX □M
-0	Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSL3 □M
<b>?</b>	Bend resistant Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSLB3 □M
.9	Long-distance Camera Cable Cable length: 15 m *2	FZ-VS4 15M
0	Long-distance Right-angle Camera Cable *1 Cable length: 15 m *2	FZ-VSL4 15M
	Cable Extension Unit Up to two Extension Units and three Cables can be connected. (Maximum cable length: 45 m *2)	FZ-VSJ

The image acquisition time does not include the image conversion processing time of the sensor controller.

The camera image input time varies depending on the sensor controller model, number of cameras, and camera settings. Check before you use the camera. Up to four cameras of this model can be connected to one controller. Up to eight cameras including other models can be connected to an FH-5550-20, 5050-20 or 2050-20.

This Cable has an L-shaped connector on the Camera end.
The maximum cable length depends on the camera being connected, and the model and length of the cable being used. For further information, refer to the Cameras / Cables Connection Table and Maximum Extension Length Using Cable Extension Units FZ-VSJ table.
When a High-speed Digital CMOS Camera FH-S\(\sigma 02/-S\sigma 04/-S\sigma 12/-S\sigma 21R\) is used in the high speed mode of transmission speed, two camera cables are

Insert the cables length into  $\square$  in the model number as follows. 2 m = 2, 3 m = 3, 5 m = 5, 10 m = 10

#### **Cameras / Cables Connection Table**

					High-sp	eed Digital CMOS	cameras			
			300,000-pixel	2 million-pixel FH-SM02/SC02		4 millio	n-pixel	12 million-pixel FH-SM12/SC12		
Camera Cables	Model	Cable	FH-SM/SC			FH-SM	04/SC04			
		length	1	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	
		2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cables Right-angle	FZ-VS3 FZ-VSL3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	Yes	No	Yes	No	Yes	No	Yes	
Bend resistant	FZ-VSB3 FZ-VSLB3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables Bend resistant		3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cable		10 m	Yes	No	Yes	No	Yes	No	Yes	
Super Bend resistant	FZ-VSBX	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cable	FZ-VODA	10 m	Yes	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	No	Yes	

				High-speed Digital CMOS cameras							
			400,00	0-pixel	5 millio	on-pixel	12 million-pixel				
Camera Cables	Model	Cable	FH-SMX/SCX		FH-SMX	05/SCX05	FH-SMX12/SCX12				
		length	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select			
		2 m	Yes	Yes	Yes	Yes	Yes	Yes			
Camera Cables	FZ-VS3 FZ-VSL3	3 m	Yes	Yes	Yes	Yes	Yes	Yes			
Right-angle camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes			
		10 m	No	Yes	No	Yes	No	Yes			
Bend resistant	FZ-VSB3 FZ-VSLB3	2 m	Yes	Yes	Yes	Yes	Yes	Yes			
camera cables Bend resistant		3 m	Yes	Yes	Yes	Yes	Yes	Yes			
Right-angle		5 m	Yes	Yes	Yes	Yes	Yes	Yes			
Camera Cable		10 m	No	Yes	No	Yes	No	Yes			
Super Bend	FZ-VSBX	5 m	Yes	Yes	Yes	Yes	Yes	Yes			
resistant Camera Cable	FZ-VSBX	10 m	No	Yes	No	Yes	No	Yes			
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	No	Yes	No	Yes	No	Yes			

				Digital CM	OS Camera		Digital CC	D cameras
			5 million-pixel 20.4 million-pixel			5 million-pixel	300,000-pixel	2 million-pixel
Camera Cables	Model	Cable length	FH-SM05R/ SC05R	FH-SM21	R/SC21R	FZ-S5M3/ SC5M3	FZ-S/SC	FZ-S2M/SC2M
		3.	-	High speed mode of transmission speed select	Standard mode of transmission speed select	-	-	-
		2 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cables Right-angle	FZ-VS3 FZ-VSL3	3 m	Yes	Yes	Yes	Yes	Yes	Yes
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	No	Yes	No	Yes	Yes
Bend resistant	FZ-VSB3 FZ-VSLB3	2 m	Yes	Yes	Yes	Yes	Yes	Yes
camera cables Bend resistant		3 m	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle		5 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cable		10 m	Yes	No	Yes	No	Yes	Yes
Super Bend	EZ VODY	5 m	Yes	Yes	Yes	Yes	Yes	Yes
resistant Camera Cable	FZ-VSBX	10 m	Yes	No	Yes	No	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	Yes

Camera Cables	Model	Cable	Small digital CCD cameras Pen type / flat type	Intelligent Compact Digital CMOS Camera
Camera Cables	Wiodei	length	FZ-SF/SFC FZ-SP/SPC	FZ-SQ□
		2 m	Yes	Yes
Camera Cables Right-angle	FZ-VS3	3 m	Yes	Yes
camera cables	FZ-VSL3	5 m	Yes	Yes
		10 m	Yes	Yes
Bend resistant	FZ-VSB3 FZ-VSLB3	2 m	Yes	Yes
amera cables Bend resistant		3 m	Yes	Yes
Right-angle		5 m	Yes	Yes
amera Čable		10 m	Yes	Yes
Super Bend esistant	FZ-VSBX	5 m	Yes	Yes
Camera Cable	FZ-VODA	10 m	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	Yes

#### Maximum Extension Length Using Cable Extension Units FZ-VSJ

		Transmission	No. of CH used	Maximum cable length	Max. number of	Using Cable Extension Units FZ-VSJ		
Item	Model	speed (*1)	for connection (*2)	using 1 Camera Cable (*1)	connectable Extension Units	Max.cable length	Connection configuration	
	FH-SM/SC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
	FH-SMX/SCX	Standard		15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
	PH-SWA/SCA	High speed		5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
High-speed Digital CMOS Cameras		Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
	FH-SM02/SC02 FH-SM04/SC04	Standard	2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: 15 m × 6 Extension Unit: 4	
	FH-SM12/SC12 FH-SMX05/SCX05 FH-SMX12/SCX12	High speed	1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
		Trigit speed	2	5 m (Using FZ-VS□/VSL□)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m × 6 Extension Unit: 4	
	FH-SM21R/SC21R	Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
			2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: 15 m × 6 Extension Unit: 4	
Digital CMOS			1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
Cameras		High speed	2	5 m (Using FZ-VS□/VSL□)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m × 6 Extension Unit: 4	
	FH-SM05R/SC05R			15 m (Using FZ-VS□/VSL□)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
	FZ-S5M3/SC5M3			5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
Digital CCD Cameras	FZ-S/SC FZ-S2M/SC2M			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
Small Digital CCD Cameras Flat type/ Pen type	FZ-SF/SFC FZ-SP/SPC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
Intelligent Compact Digital CMOS Camera	FZ-SQ□			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	

<sup>\*1</sup> The FH-S — enables switching between standard and high speed modes. In high speed mode, images can be transferred approximately two times faster than in standard mode, but the connectable cable length will be shorter.

<sup>\*2</sup> The FH-S has two channels to connect Camera Cables. Connection to two channels makes image transfer two times faster than connection to one channel: high speed mode using two channels can transfer approximately four times as many images as standard mode using one channel.

<sup>\*3</sup> Each channel can be used to connect up to two Cable Extension Units: up to four extension units, two channels x two units, can be connected by using two channels.

#### **Connection Configuration**

	Connection configuration using the maximum length of Camera Cables	Remarks
Configuration 1	15 m 15 m 15 m (2) (3)	
Configuration 2	CH1 15 m 15 m 15 m 15 m (1) (2) (3) (3) 15 m 15 m CH2 (4) (5) (6)	Camera cable connector CH2 Camera cable connector CH1
Configuration 3	5 m 5 m 5 m (1) (2) (3)	
Configuration 4	CH1 5 m 5 m 5 m 5 m	Camera cable connector CH2 Camera cable connector CH2 CH1

Select the Camera Cables between the Controller and Extension Unit, between the Extension Units, and between the Extension Unit and Camera according to the Different types or lengths of Camera Cables can be used for (1), (2), and (3) as well as for (4), (5), and (6). However, the type and length of Camera Cable (1) must be the same as those of Camera Cable (4), (2) must be the same as (5), and (3) must be the same as (6).

#### **Monitor**

Item	Descriptions	Model
	Touch Panel Monitor 12.1 inches For FH Sensor Controllers *	FH-MT12
	LCD Monitor 8.4 inches	FZ-M08

<sup>\*</sup> FH Series Sensor Controllers version 5.32 or higher is required.

#### **Monitor Cables**

Item	Descriptions	Model
	DVI-Analog Conversion Cable for Touch Panel Monitor/LCD Monitor Cable length: 2 m, 5 m or 10 m	FH-VMDA □M *1
	RS-232C Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	XW2Z-□□□PP-1 *2
19	USB Cable for Touch Panel Monitor Cable length: 2 m or 5 m	FH-VUAB □M *1

<sup>\*1</sup> Insert the cables length into  $\square$  in the model number as follows. 2 m = 2, 5 m = 5, 10 m = 10

A video signal cable and an operation signal cable are required to connect the Touch Panel Monitor.

Signal	Cable	2 m	5 m	10 m
Video signal	DVI-Analog Conversion Cable	Yes	Yes	Yes
Touch panel operation	USB Cable	Yes	Yes	No
signal	RS-232C Cable	Yes	Yes	Yes

#### Parallel I/O Cables/Encoder Cable

Item	Descriptions	Model
7	Parallel I/O Cable *1 Cable length: 2m, 5m or 15m	<b>XW2Z-S013-</b> □ *2
	Parallel I/O Cable for Connector-terminal Conversion Unit *1 Cable length: 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m Connector-Terminal Block Conversion Units can be connected (Terminal Blocks Recommended Products: OMRON XW2K-34G-T)	<b>XW2Z-</b> □□□ <b>EE</b> *3
	Ultra-Compact Interface Wiring System (General-Purpose)	XW2K-34G-T *4
0	Encoder Cable for line-driver Cable length: 1.5 m	FH-VR 1.5M

<sup>2</sup> Cables are required for all I/O signals.

<sup>\*2</sup> Insert the cables length into  $\square\square\square$  in the model number as follows. 2 m = 200, 5 m = 500, 10 m = 010.

Insert the cables length into in the model number as follows. 2 m = 2, 5 m = 5, 15 m = 15
Insert the cables length into in the model number as follows. 0.5 m = 050, 1 m = 100, 1.5 m = 150, 2 m = 200, 3 m = 300, 5 m = 500
Refer to the XW2K Series Datasheet (Cat. No. G152) for details.

#### **Parallel Converter Cable**

When you change to connect the F series, FZ5 series, or FZ5-L series to FH series Sensor Controller, you can convert by using the appropriate parallel converter cable of FH-VPX series under the usable condition.

Item	Арр	licable Model	Usable Condition	Model	
	FZ⊡ series		Do not use RESET signal. *     Use with COMIN and COMUT are same power source.	FH-VPX-FZ	
~	FZ□-L35x series		Do not use RESET signal. *	FH-VPX-FZL	
	F160 series	F160-C10	Do not use RESET signal.*     Use with COMIN and COMOUT are same power source.     Do not use DI5 and DI6.	FH-VPX-F160	
	F210 series	F210-C10	Do not use RESET signal. *		
<b>(</b>	1 2 10 301163	F210-C10-ETN	Use with COMIN and COMOUT are same power source.	FH-VPX-F210	
	F500 series F500-C10		Do not use DI8 and DI9.		

<sup>\*</sup> Even if RESET signal cannot be use by conversion, conversion is possible to convert satisfying other usable condition. **Note:** Cannot be used for the F160-C10CP/-C10CF.

#### Recommended EtherCAT and EtherNet/IP Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT. Use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for EtherNet/IP.

Cable with Connectors

ltem	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6LSZH8SS30CM-Y
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1		OMRON	1	XS6W-6LSZH8SS100CM-Y
Wire Gauge and Number of Pairs: AWG26, 4-pair Cable Cable Sheath material: LSZH *2		OWRON	2	XS6W-6LSZH8SS200CM-Y
Cable color: Yellow *3			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	-		0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1	**	OMRON	1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			2	XS5W-T421-DMD-K
Cable color: Light blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
		OMRON	0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4			2	XS5W-T421-DM2-SS
M12/Smartclick Connectors			3	XS5W-T421-EM2-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GM2-SS
Capic colon Diagn			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *4			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	100	OMRON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type		OIVIRON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

<sup>\*1</sup> Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the Industrial Ethernet Connectors Catalog (Cat. No. G019).

<sup>\*2</sup> The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PÚR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

<sup>\*3</sup> Cables colors are available in yellow, green, and blue.

<sup>\*4</sup> For details, contact your OMRON representative.

#### **FH-Series**

#### Cables / Connectors

Ite	em	Recommended manufacturer	Model
Products for EtherCAT or EtherNet/IP	Cable	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P CP *1
(1000BASE-T/100BASE-TX) Wire gauge and number of pairs:	Cable	Kuramo Electric Co.	KETH-SB *1
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C <b>*1</b>
	Cabla	Kuramo Electric Co.	KETH-PSB-OMR *2
Products for EtherCAT or EtherNet/IP	Cable	JMACS Japan Co., Ltd.	PNET/B *2
(100BASE-TX/10BASE-T) Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 <b>*2</b>

<sup>\*1</sup> We recommend you to use the above Cable and RJ45 Connector together.

Automation Software Sysmac Studio

Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Marina	Supplifications		Model	
Item	Specifications	Number of licenses	Media	Wodei
	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of	(Media only)	Sysmac Studio (32bit) DVD *2	SYSMAC-SE200D
	machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCat Slave, and the HMI.	(Media only)	Sysmac Studio (64bit) DVD *2	SYSMAC-SE200D-64
Sysmac Studio Standard Edition	Sysmac Studio runs on the following OS. *1 Windows 7 (32-bit/64-bit version) / Windows 8.1 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version) / Windows 11 (64-bit version) This software provides functions of the Vision Edition. Refer to OMRON website for details such as supported models and functions.	1 license	_	SYSMAC-SE201L
Ver.1.□□		3 license	_	SYSMAC-SE203L
		10 license	_	SYSMAC-SE210L
		30 license	_	SYSMAC-SE230L
		50 license	_	SYSMAC-SE250L
Sysmac Studio Vision Edition Ver.1 *3 *4	Sysmac Studio Vision Edition is a limited license that provides selected functions required for Vision Sensor FH-series/ Smart Camera FHV7-series/FQ-M-series settings.	1 license	_	SYSMAC-VE001L
Sysmac Studio Robot Additional Option *4	Sysmac Studio Robot Additional Option is a license to enable the Vision & Robot integrated simulation.	1 license	_	SYSMAC-RA401L

Site licenses are available for users who will run Sysmac Studio on multiple computers. Ask your OMRON sales representative for details.
 Sysmac Studio version 1.07 or higher supports the FH Series. Sysmac Studio does not support the FH-L551/-L551-10.

#### **Development Environment**

Please purchase a CD-ROM and licenses the first time you purchase the Application Producer. CD-ROMs and licenses are available individually. The license does not include the CD-ROM.

Product	Specifications	Number of Model Standards licenses	Media	Model
	Software components that provide a development environment to further customize the standard controller features of the FH Series. System requirements: CPU: Intel Pentium Processor (SSE2 or higher) OS: Windows 7 Professional (32/64bit) or Enterprise(32/64bit) or Ultimate (32/64bit), Windows 8 Pro (32/64bit) or Enterprise (32/64bit),	— (Media only)	CD-ROM	FH-AP1
Application Producer	Windows 8.1 Pro (32/64bit) or Enterprise (32/64bit), Windows 10 Pro (32/64bit) or Enterprise (32/64bit) .NET Framework: .NET Framework 3.5 SP1 or higher Memory: At least 2 GB RAM Available disk space: At least 2 GB Browser: Microsoft® Internet Explorer 6.0 or later Display: XGA (1024 × 768), True Color (32-bit) or higher Optical drive: CD/DVD drive The following software is required to customize the software: Microsoft® Visual Studio® 2008 Professional or Microsoft® Visual Studio® 2010 Professional	1 license	_	FH-AP1L

<sup>\*2</sup> We recommend you to use the above Cable and RJ45 Assembly Connector together.

Model "SYSMAC-SE200D-64" runs on Windows 10 (64bit) or higher.

The same media is used for both the Standard Edition and the Vision Edition.

With the Vision Edition, you can use only the setup functions for FH-series/FQ-M-series Vision Sensors.

This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it.

#### **Accessories**

Item		Descriptions			Model		
	USB Memory		2 GB		FZ-MEM2G		
(H	GGB Welliory		16 GB				
1 400 at.	SD Card		2 GB		HMC-SD292 *2		
	OB Gard		4 GB		HMC-SD492 *2		
	Display/USB Switcher						
-	Driverless wired mouse	se Recommended Products erless wired mouse house that requires the mouse driver to be installed is not supported.)					
12.0C	EtherCAT junction slaves	3 port	Power supply voltage: 20.4 to 28.8 VDC	Current consumption: 0.08 A	GX-JC03		
20 20 20 20 20 20 20 20 20 20 20 20 20 2	EtherCAT junction slaves	6 port	(24 VDC -15 to 20%)	Current consumption: 0.17 A	GX-JC06		
666	Industrial Switching Hubs for EtherNet/IP and Ethernet	5 port		Current consumption: 0.07 A	W4S1-05D		
_	Calibration Plate	1		-	FZD-CAL		
		DIN rail mounting bracket (For Lite Controllers)					
	Common items related to DIN rail	DIN 35mm rail	PHOENIX CONTACT	<ul><li>Length: 75.5/95.5/115.5/200 cm</li><li>Height: 7.5mm</li><li>Material: Iron</li><li>Surface: Conductive</li></ul>	NS 35/7,5 PERF		
	(for FH-L551/-L551-10)			Length:75.5/95.5/115.5/200 cm Height: 15mm Material: Iron Surface: Conductive	NS 35/15 PERF		
		End plate	PHOENIX CONTACT	Need 2 pieces each Sensor Controller	CLIPFIX 35		
		I		LED	FLV Series		
			External lighting controller	High-brightness LED	FL-BR/DR Serie		
_	External Lights *1		59	Photometric Stereo Light	FL-PS Series		
			Built-in lighting controller	MDMC Light	FL-MD Series		
			Dunt-in lighting controller	IVIDINO LIGIT	FE-MID Selles		
-1				Mounting Bracket	FQ-XL		
	For Intelligent Compact Di	For Intelligent Compact Digital CMOS Camera		Mounting Brackets	FQ-XL2		
				Polarizing Filter Attachment	FQ-XF1		
	Mounting Bracket for FZ-S	□, FH-S□05R <u>,</u> FZ	Z-S□X		FZ-S-XLC		
	Mounting Bracket for FZ-S	□2M			FZ-S2M-XLC		
_	Mounting Bracket for FH-S	□, FZ-S□5M□, F	H-S□X05, FH-S□X12, FH-S□2		FH-SM-XLC		
	Mounting Bracket for FH-S	i□12			FH-SM12-XLC		
	M42 - F Mount Conversion	Adapter			FH-ADF/M42-10		

#### **Recommended SD Cards**

For inquiries regarding the purchase and specifications of these products, please contact below.

Item	Recommended manufacturer	Capacity	Model	Contact
2-	HAGIWARA Solutions Co., Ltd.	2 GB	NSD6-002GS(P11SEI	Inquiry of purchase Sales Agencies https://www.hagisol.com/dealer/
1 4. - e:		4 GB	NSD6-004GS(P11SEI	Inquiry of specification HAGIWARA Solutions Co., Ltd. https://www.hagisol.com/support/

<sup>\*1</sup> Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.
\*2 This SD card cannot be used with the FH-L551/-L551-10. Use the recommended SD cards listed below.

#### **FH-Series**

#### Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens			
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens	Vibrations and Shocks Resistant Lens	
	FZ-SF/SFC		FZ-LES Series			
300,000-pixel	FZ-SP/SPC	1/2" aguirelant	FZ-LES Series			
	FZ-S/SC	- 1/3" equivalent				
	FH-SM/SC		SV-V Series	VS-TCH Series	VS-MCA Series Non-telecentric Macro VS-MC Series	
400,000-pixel	FH-SMX/SCX	1/2.9" equivalent		VS-10H Selles		
2 million nivel	FZ-S2M/SC2M	1/1.8" equivalent	SV-H Series			
2 million-pixel	FH-SM02/SC02	2/3" equivalent *1	VS-H1 Series	VS-TEV Series	VS-MCA Series	
4 million-pixel	FH-SM04/SC04	1" equivalent	VS-HT Selles	VS-TEV Selles	VS-MCH1 Series	
	FH-SM05R/SC05R	1/2.5" equivalent			VS-MCA Series	
5 million-pixel	FZ-S5M3/SC5M3	2/3" equivalent	SV-H Series	VS-TCH Series	Non-telecentric Macro	
	FH-SMX05/SCX05	2/3" equivalent			VS-MC Series	
12 million-pixel	FH-SMX12/SCX12	1.1" equivalent	VS-LLD Series VS-HVA Series	VS-TEV Series		
	FH-SM12/SC12	1.76" equivalent	VS-L/M42-10 Series		VS-MCL/M42-10 Series	
20.4 million-pixel	FH-SM21R/SC21R	1" equivalent	VS-LLD Series VS-HVA Series	VS-TEV Series	VS-MCH1 Series	

<sup>\*1</sup> A lens recommended for a 1" image element should be used for an image element size equivalent to 2/3". Vignetting may occur with a lens recommended for a 2/3" image element.

### **Ratings and Specifications (FH Sensor Controllers)**

### High-speed, Large-capacity Controller

Sensor Controller Series Sensor Controller Model		FH-5550/5050	FH-5550/5050 Series FH-5550/5050-10	FH-5550/5050-20	FH-2050	FH-2050 Series FH-2050-10	FH-2050-20			
Parallel IO		NPN/PNP (common)		+		•				
Memory, Storage			FH-5550 series : 32G FH-5050 series : 8GE			8GB RAM, 32GB RO	MC			
Number of cor	es		4 cores	4 cores 2 cores						
		Standard  Double Speed Multi-input	Yes Yes							
	Operation Mode	Non-stop adjustment mode	Yes							
		Multi-line random-trigger mode	Yes (Maximum 8 lines	s) *1						
	Parallel Proces		Yes	T a			Ta			
	Number of Con	nectable Camera	2	4	8 All of the FH-S series	2	4	8 All of the FH-S ser		
	Supported	FH-S series camera	All of the FH-S series connectable.	cameras are	cameras are	All of the FH-S serie connectable.	s cameras are	cameras are		
Main Functions	Camera	FZ-S series camera	All of the FZ-S series	cameras are connecta	connectable. *2			connectable. *2		
uncuons	Camera I/F	. 2 0 001.00 04.11014	OMRON I/F	Samoras are semiesta						
		er of Captured Images	Refer to page 31.							
	Possible Number	of Logging Images to Sensor Controller	Refer to the Vision Sy 128	stem FH/FZ5 Series U	ser's Manual (Cat. No. 2	Z365).				
	Operating	USB Mouse		driver is unnecessary ty	pe)					
	on UI	Touch Panel	Yes (RS-232C/USB of							
	Setup			flow using Flow editing				5 11		
	Language Serial Commun	nication	RS-232C × 1	implified Chinese, Trad	itional Chinese, Korean	, German, French, Spa	anish, Italiah, Vietham	ese, Polish		
	Ethernet	Protocol	Non-procedure (TCP/	UDP)						
	Communication		1000BASE-T × 2							
	EtherNet/IP Co		Yes (Target/Ethernet Yes (Slave/Etherne							
	PROFINET Con	nmunication	Yes (Slave/Etnerne)     Conformance class							
	EtherCAT Com	munication			T Communications Spe	cifications.				
			<ul> <li>12 inputs/31 outputs</li> <li>Use 1 Line.</li> </ul>	S:						
			Operation mode:	Except Multi-line rando	m-trigger mode.					
			<ul> <li>17 inputs/37 outputs</li> <li>Use 2 Lines.</li> </ul>	3:						
External	Parallel I/O		<ul> <li>Operation mode:</li> </ul>	Multi-line random-trigg	er mode.					
Interface			<ul> <li>14 inputs/29 outputs</li> <li>Use 3 to 4 Lines.</li> </ul>	s:						
			<ul> <li>Operation mode:</li> </ul>	Multi-line random-trigg	er mode.					
			<ul> <li>19 inputs/34 outputs</li> <li>Use 5 to 8 Lines.</li> </ul>	s:						
			Operation mode: Multi-line random-trigger mode.							
	Encoder Interface		Input voltage: 5 V ± 5% Signal: RS-422A Line Driver Level							
	Encoder interface		Pňase A/B/Z: 1 MHz							
	Monitor Interface		DVI-I output (Analog RGB & DVI-D single link) × 1  USB3.0 host × 2 (BUS Power: Port5 V/0.5 A)							
	USB I/F		USB2.0 host × 4 (BUS Power: Port5 V/0.5 A)							
	SD Card I/F		SDHC×1							
	Main		POWER: Green ERROR: Red							
			RUN: Green ACCESS: Yellow							
			NET RUN1: Green							
Indicator	Ethernet		LINK/ACT1: Yellow NET RUN2: Green							
Lamps				LINK/ACT2: Yellow						
	SD Card		SD POWER: Green SD BUSY: Yellow							
			ECAT RUN: Green							
	EtherCAT		LINK/ACT IN: Green LINK/ACT OUT: Green							
Power-supply	voltage		ECAT ERR: Red 20.4 VDC to 26.4 VD	r:						
OHCI-Supply	When connecting	an intelligent compact digital camera	20.4 VBO to 20.4 VB	<u> </u>						
	<ul> <li>When connect</li> </ul>	ting the following light or lighting								
Current	FLV-TCC1	hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1	5.6 A max.	7.7 A max.	12.2 A max.	4.6 A max.	6.6 A max.	11.2 A max.		
consumption	<ul> <li>When connect</li> </ul>	ting the following light or light-								
	ing controller FL-TCC1P	S, FL-MD⊟MC								
	Other than abo	ve	4.5 A max.	5.5 A max.	7.3 A max.	3.5 A max.	4.3 A max.	6.3 A max.		
Built-in FAN			Yes Operating: 0°C to ±45	5°C		Operating: 0°C to 15	50°C			
	Ambient tempe	erature range	Operating: 0°C to +45°C Storage: -20 to +65°C (with no icing or condensation)  Operating: 0°C to +50°C Storage: -20 to +65°C (with no icing or condensation)							
	Ambient humid	lity range	Operating:35 to 85%RH							
	Ambient atmos	sphere	Storage: 35 to 85%RH (with no condensation)  No corrosive gases							
			Oscillation frequency: 10 to 150 Hz							
	Vibration tolera	anco	Half amplitude: 0.1 mm Acceleration: 15 m/s <sup>2</sup>							
Jsage Environment	VIDIALION LOIETA	nice	Sweep time: 8 minute/count Sweep count: 10							
			Vibration direction: up and down/front and behind/left and right							
	Shock resistan	се	Impact force: 150 m/s <sup>2</sup> Test direction: up and down/front and behind/left and right							
	Nois-		• DC power							
	Noise immunity	Fast Transient Burst	Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 m • I/O line							
			Type D grounding (100 Ω or less grounding resistance) *3							
	Grounding		Type D grounding (10 190 mm × 115 mm ×		esistance) *3					
	Dimensions		Note Height: Including	the feet at the base.						
eatures	Weight	-41	Approx. 3.4 kg	Approx. 3.6 kg	Approx. 3.6 kg	Approx. 3.0 kg	Approx. 3.2 kg	Approx. 3.2 kg		
catures	Degree of prote	есиоп	IEC60529 IP20 Cover: zinc-plated ste	eel plate						
	Case material		Side plate: aluminum	(A6063)						
Accessories			Instruction Sheet (Jap General Compliance	panese and English): 1	Installation Instruction tions for EU:1, Member	Manual for FH series:1	1, Power source (FH-XCt	N): 1 (male)		
			Ferrite core for camer	a cable: 2 (FH-5□50 F	H-2050), 4 (FH-5□50-1	IN FH-2050-10\ 8 (FH	1 E E O O E L O O O	n),		

<sup>\*1</sup> According to the CPU performance, FH-2050 series is recommended to use up to two lines in this mode.
\*2 Up to eight cameras can be connected in total including up to four 12 or 20.4 million-pixel cameras.
\*3 Existing third class grounding

#### **Lite Controllers**

Sensor Control	ler Series		FH.I 55:	1 Series			
Sensor Control			FH-L551	FH-L551-10			
Parallel IO			NPN/PNP (common)				
Memory, Storag	je		4GB RAM, 32GB ROM				
		Standard	Yes Yes				
		Double Speed Multi-input Non-stop adjustment					
	Operation Mode	mode	Yes				
		Multi-line random-trigger mode	No				
	Parallel Processin	<u> </u>	Yes				
	Number of Conne		2	4			
Main Func-	Supported Camera	FH-S series camera FZ-S series camera	All of the FH-S series cameras except FH-SM21R/SC21R  All of the FZ-S series cameras are connectable.				
tions	Camera I/F	1 2-0 Series Califera	OMRON I/F				
	Possible Number	of Captured Images	Refer to page 31.				
		of Logging Images to	Refer to the Vision System FH/FZ5 Series User's Manual (Cat. No. Z	365).			
	Sensor Controller Possible Number		128				
		USB Mouse	Yes (wired USB driver-less type)				
	UI Operations	Touch Panel	Yes (RS-232C/USB connection: FH-MT12)				
	Setup	Į.	Create the processing flow using Flow editing.				
	Language		Japanese, English, Simplified Chinese, Traditional Chinese, Korean,	German, French, Spanish, Italian, Vietnamese, Polish			
	Serial Communica		RS-232C × 1				
	Ethernet Communication	Protocol I/F	Non-procedure (TCP/UDP) 1000BASE-T × 1				
	EtherNet/IP Communication		Yes (Target/Ethernet port)				
	PROFINET Communication		Yes (Slave/Ethernet port)				
	EtherCAT Communication		Conformance class A				
External	EtherCAT Commi	unication	No High-speed input: 1				
Interface	Parallel I/O		Normal speed: 9				
	T drailer i/O		High-speed output: 4     Normal speed: 23				
	Encoder Interface	)	None				
	Monitor Interface		DVI-I output (Analog RGB & DVI-D single link) × 1				
	USB I/F		USB2.0 host × 1: BUS Power: Port 5 V/0.5 A				
	SD Card I/F		USB3.0 × 1: BUS Power: Port 5 V/0.5 A  SDHC × 1				
	02 04.4 8.		POWER: Green				
	Main		ERROR: Red RUN: Green				
			ACCESS: Yellow				
Indicator Lamps	Ethernet		NET RUN: Green LINK/ACT: Yellow				
			SD POWER: Green				
	SD Card		SD BUSY: Yellow				
	EtherCAT		None				
Power-supply v		an intelligent compact dig-	20.4 VDC to 26.4 VDC				
	ital camera	an intelligent compact dig-					
		g the following light or					
Current	power supply	er without an external	2.7 A max.	4.4 A max.			
consumption	FLV-TCC1, FI FLV-TCC1EP	LV-TCC4, FLV-TCC3HB	2.77(1104).	T.T / VIIIGA.			
	<ul> <li>When connecting</li> </ul>	ig the following light or					
	lighting controll FL-TCC1PS, I						
	Other than above		1.5 A max.	2.0 A max.			
Built-in FAN			No				
	Ambient temperat	ture range	Operating: 0°C to 55°C Storage: -25 to +70°C				
	Ambient humidity	range	Storage: -25 to +70°C  Operating and Storage: 10 to 90%RH (with no condensation)				
	Ambient atmosph		No corrosive gases				
	Vibration tolerand	e	5 to 8.4 Hz with 3.5 mm amplitude, 8.4 to 150 Hz, acceleration of 9.8 m/s² 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)				
Usage Envi- ronment	Shock resistance		Impact force: 150 m/s² Test direction: up and down/front and behind/left and right				
	Noise	Foot Toronto ( D	DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 min				
	immunity	Fast Transient Burst	//O line     Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns,     Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 min				
	Grounding		Type D grounding (100 $\Omega$ or less grounding resistance) *	IIIV. 1 IIIIII			
	Dimensions		200 mm × 80 mm × 130 mm				
External	Weight		Approx. 1.5 kg	Approx. 1.5 kg			
Features	Degree of protect	ion	IEC60529 IP20				
	Case materials		PC Instruction Sheet (Japanese and English): 1, Installation Instruction M	Janual for EH-L cariac-1			
Accessories	i		Instruction Sheet (Japanese and English): 1, installation instruction M General Compliance Information and Instructions for EU:1, Member of Power source (FH-XCN-L):1 (male)				

<sup>\*</sup> Existing third class grounding

#### Maximum Number of Loading Images during Multi-input

Camera	Model	Max. Number of Loading Images during Multi-input *1		
Intelligent Compact Digital CMOS Cameras *2	FZ-SQ010F/-SQ050F/-SQ100F/-SQ100N	256		
0.3 million pixels CCD/CMOS Cameras	FZ-S/-SC/-SF/SFC/-SH/-SHC/-SP/-SPC FH-SM/-SC	256		
0.4 million pixels CMOS Cameras	FH-SMX/-SCX	256		
2 million pixels CCD Cameras	FZ-S2M/-SC2M	64		
2 million pixels CMOS Cameras	FH-SM02/-SC02	51		
4 million pixels CMOS Cameras	FH-SM04/-SC04	32		
5 million pixels CCD/CMOS Cameras	FZ-S5M3/-SC5M3/-S5M2 FH-SMX05/-SCX05/-SM05R/-SC05R	25		
12 million pixels CMOS Cameras	FH-SM12/-SC12/-SMX12/-SCX12	10		
20.4 million pixels CMOS Cameras	FH-SM21R/-SC21R	6		

When using two camera cables for connection, the maximum number of loaded images during multi-input is twice the number given in the table. The multi-input function cannot be used when the built-in light of an intelligent compact digital camera is used. Refer to the Vision System FH/FZ5 Series User's Manual (Cat. No. Z340) for details.

#### **FH-Series**

### **Ratings and Specifications (Cameras)**

#### **High-speed Digital CMOS cameras**

Model	FH-SM	FH-SC	FH-SM02	FH-SC02	FH-SM04	FH-SC04	FH-SM12	FH-SC12
Image elements				CMOS image elements (2/3-inch equivalent) *1		CMOS image elements (1-inch equivalent)		elements valent)
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color	Monochrome	Color
Effective pixels	640 (H) × 480 (\	/)	2040 (H) × 1088	3 (V)	2040 (H) × 2048	3 (V)	4084 (H) × 307	2 (V)
Pixel size	7.4 (μm) × 7.4 (μm)		$5.5  (\mu m) \times 5.5  (\mu m)$	μm)	$5.5  (\mu m) \times 5.5  (\mu m)$	μm)	$5.5  (\mu m) \times 5.5  (\mu m)$	(μm)
Shutter function	Electronic shutter; Shutter speeds can be set from 20 μs to 100 ms.		Electronic shutter; Shutter speeds can be set from 25		5 μs to 100 ms.		Electronic shutter; Shutter speeds can be set from 60 μs to 100 ms.	
Partial function	1 to 480 lines	2 to 480 lines	1 to 1088 lines	2 to 1088 lines	1 to 2048 lines	2 to 2048 lines	4 to 3072 lines (4-line increments)	
Frame rate (Image Acquisition Time *2)	308 fps (3.3 ms	)	219 fps (4.6 ms) *3		118 fps (8.5 ms) *3		38.9 fps (25.7 ms) *3	
Lens mounting	C mount					M42 mount		
Field of vision, installation distance	Selecting a lens	according to the	field of vision and	l installation dista	nce			
Ambient temperature range	Operating: 0 to	40 °C, Storage: -:	25 to 65 °C (with r	no icing or conder	nsation)			
Ambient humidity range	Operating and s	storage: 35% to 8	5% (with no conde	ensation)				
Weight	Approx.105 g		Approx.110 g			Approx.320 g		
Accessories	Instruction man	ual						

Model	FH-SMX	FH-SCX	FH-SMX05	FH-SCX05	FH-SMX12	FH-SCX12	
Image elements	CMOS image elements (1/2.9-inch equivalent)		CMOS image element	CMOS image elements (2/3-inch equivalent)		CMOS image elements (1.1-inch equivalent)	
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color	
Effective pixels	720 (H) × 540 (V)		2448 (H) × 2048 (V)		4092 (H) × 3000 (V)		
Pixel size	6.9 (μm) × 6.9 (μm)		$3.45 \ (\mu m) \times 3.45 \ (\mu m)$	)			
Shutter function	Electronic shutter; Shutter speeds can be	e set from 1 μs to 100 r	ns.		Electronic shutter; Shutter speeds can be	set from 15 µs to 100 ms.	
Partial function	4 to 540 lines (4-line increments)		4 to 2048 lines (4-line increments)		4 to 3000 lines (4-line increments)		
Frame rate (Image Acquisition Time *2)	523.6 fps (1.9 ms)		97.2 fps (10.3 ms) *3		40.1 fps (24.9 ms) *3		
Lens mounting	C mount						
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance						
Ambient temperature range	Operating: 0 to 50 °C, Storage: -25 to 65 °C (with no icing or condensation)  Operating: 0 to 40 °C, Storage: -25 to 65 °C (with no icing or condensation)						
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)						
Weight	Approx.48 g Approx.85 g						
Accessories	,	Instruction manual, General Compliance Information and Instructions for EU					

<sup>1</sup> A lens recommended for a 1" image element should be used for an image element size equivalent to 2/3". Vignetting may occur with a lens recommended for a 2/3" image element.

#### **Digital CMOS Cameras**

Model	FH-SM05R	FH-SC05R	FH-SM21R	FH-SC21R	FZ-S5M3	FZ-SC5M3
Image Elements	CMOS image elements	(1/2.5-inch equivalent)	CMOS image elemen	ts (1-inch equivalent)	CMOS image elements (2/3-inch equivalent)	
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color
Effective Pixels	2592 (H) × 1944 (V)		5544 (H) × 3692 (V)		2448 (H) × 2048 (V)	
Pixel Size	2.2 (μm) × 2.2 (μm)		2.4 (μm) × 2.4 (μm)		3.45 (µm) × 3.45 (µm)	)
Scan Type	Progressive					
Shutter Method	Rolling shutter (Globa	I reset mode supported	)		Global shutter	
Shutter Function	Electronic shutter; Shutter speeds can be set from 500 μs to 100 ms in multiples of 50 μs		Electronic shutter; Shutter speeds can be set from 50 μs to 100 ms.		Electronic shutter; Shutter speeds can be set from 20 μs to 100 ms.	
Partial function	4 to 1944 lines (2-line	increments)	1848 to 3692 lines		4 to 2048 lines	
Frame rate (Image Acquisition Time *)	14 fps (71.7ms)		23.5 fps (42.6ms)		25.6 fps (38.2ms)	
Lens Mounting	C mount	2 mount				
Field of vision, Installation distance	Selecting a lens acco	Selecting a lens according to the field of vision and installation distance				
Ambient temperature range	Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or condensation)		Operating: 0 to +40°C Storage: -20 to 65°C (with no icing or condensation)		Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or cond	
Ambient humidity range	Operating: 35 to 85%RH, Storage: 35 to 85%RH (with no condensation)					
Weight	Approx. 52 g Approx. 85 g					
Accessories	Instruction Sheet		Instruction Sheet, General Compliance Information		mation and Instructions for EU	

<sup>\*</sup> The image acquisition time does not include the image conversion processing time of the sensor controller.

a 2/3" image element.

\*2 The image acquisition time does not include the image conversion processing time of the sensor controller.

\*3 Frame rate in high speed mode when the camera is connected using two camera cables.

### **Digital CCD Cameras**

Model	FZ-S	FZ-SC	FZ-S2M	FZ-SC2M	
Image elements	Interline transfer reading all pixel CCD image elements (1/3-inch e		Interline transfer reading all pixels, CCD image elements (1/1.8-inch equivalent)		
Color/Monochrome	Monochrome	Color	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)		1600 (H) × 1200 (V)		
Pixel size	7.4 (μm) × 7.4 (μm)		4.4 (μm) × 4.4 (μm)		
Shutter function	Electronic shutter; select shutter	speeds from 20 µs to 100 ms			
Partial function	12 to 480 lines		12 to 1200 lines		
Frame rate (Image Acquisition Time *)	80 fps (12.5 ms)		30 fps (33.3 ms)		
Lens mounting	C mount				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance				
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or condensation)		Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)		
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)				
Weight	Approx. 55 g		Approx. 76 g		
Accessories	Instruction manual				

<sup>\*</sup> The image acquisition time does not include the image conversion processing time of the sensor controller.

#### **Small CCD Digital Cameras**

Model	FZ-SF	FZ-SFC	FZ-SP	FZ-SPC	
Image elements	Interline transfer reading all pixels, CCD image elements (1/3-inch equivalent)				
Color/Monochrome	Monochrome	Color	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)				
Pixel size	7.4 (μm) × 7.4 (μm)				
Shutter function	Electronic shutter; select shutter	speeds from 20 µm to 100 ms			
Partial function	12 to 480 lines				
Frame rate (Image Acquisition Time *)	80 fps (12.5ms)				
Lens mounting	Special mount (M10.5 P0.5)				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance				
Ambient temperature range	Operating: 0 to 50 °C (camera amp) 0 to 45 °C (camera head) Storage: -25 to 65 °C (with no icing or condensation)				
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)				
Weight	Approx. 150 g				
Accessories	Instruction manual, installation bracket, Four mounting brackets (M2)				

<sup>\*</sup> The image acquisition time does not include the image conversion processing time of the sensor controller.

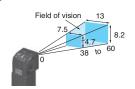
#### **FH-Series**

#### **Intelligent Compact Digital CMOS Cameras**

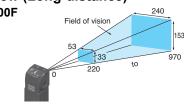
Model	FZ-SQ010F	FZ-SQ050F	FZ-SQ100F	FZ-SQ100N		
Image elements	CMOS color image elements (1	/3-inch equivalent)				
Color/Monochrome	Color					
Effective pixels	752 (H) × 480 (V)					
Pixel size	6.0 (μm) × 6.0 (μm)					
Shutter function	1/250 to 1/32,258					
Partial function	8 to 480 lines	3 to 480 lines				
Frame rate (Image Acquisition Time *1)	60 fps (16.7 ms)					
Field of vision	7.5 × 4.7 to 13 × 8.2 mm	13 × 8.2 to 53 × 33 mm	$53 \times 33$ to $240 \times 153$ mm	29 × 18 to 300 × 191 mm		
Installation distance	38 to 60 mm	56 to 215 mm	220 to 970 mm	32 to 380 mm		
LED class *2	Risk Group2		•	•		
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C					
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)					
Weight	Approx. 150 g Approx. 140 g					
Accessories	Mounting bracket (FQ-XL), pola	rizing filter attachment (FQ-XF	1), instruction manual and warning	label		

The image acquisition time does not include the image conversion processing time of the sensor controller. Applicable standards: IEC62471-2

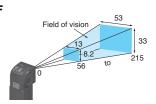
#### Narrow View FZ-SQ010F



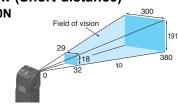
• Wide View (Long-distance) FZ-SQ100F



#### • Standard FZ-SQ050F



• Wide View (Short-distance) FZ-SQ100N



### **Ratings and Specifications (Cable, Monitor)**

#### **Camera Cables**

Model	FZ-VS3 (5 m)	FZ- VSB3 (5 m)	FZ- VSBX (5 m)	FZ- VSL3 (5 m)	FZ- VSLB3 (5 m)	
Туре	Stan- dard	Bend resistant	Super- bend- resistant	Right- angle	Bend resistant Right-angle	
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times					
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)					
Ambient humidity range		Operation and storage: 40 to 70%RH (with no condensation)				
Ambient atmosphere	No corrosive gases					
Material	Cable sheath, connector: PVC					
Minimum bending radius	69mm	69mm	69mm	69mm	69mm	
Weight	Approx. 390 g	Approx. 430 g	Approx. 460 g	Approx. 390 g	Approx. 430 g	

#### **Cable Extension Unit**

Model	FZ-VSJ
Power supply voltage *1	11.5 to 13.5 VDC
Current consumption *2	1.5 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 240 g
Accessories	Instruction Sheet and 4 mounting screws

 <sup>\*1</sup> A 12-VDC power supply must be provided to the Cable Extension Unit when connecting the Intelligent Compact Camera, or the Lighting Controller.
 \*2 The current consumption shows when connecting the Cable Extension Unit to an external power supply.

#### **Long-distance Camera Cables**

Model	FZ-VS4 (15 m)	FZ-VSL4 (15 m)		
Туре	Standard	Right-angle		
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times			
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)			
Ambient atmosphere	No corrosive gases			
Material	Cable sheath, connector: PVC			
Minimum bending radius	us 78 mm			
Weight	Approx. 1400 g			

#### **Encoder Cable**

Model	FH-VR
Vibration resistiveness	10 to 150 Hz single amplitude 0.1 mm 3 directions, 8 strokes, 10 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -10 to 60 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable Jacket: Heat, oil and flame resistant PVC Connector: polycarbonate resin
Minimum bending radius	65 mm
Weight	Approx. 104 g

#### **Touch Panel Monitor**

Model		FH-MT12
	Display area	12.1 inch
	Resolution	1024 (V) × 768 (H)
	Number of color	16,700,000 colors (8 bit/color)
	Brightness	500cd/m <sup>2</sup> (Typ)
Major Function	Contrast Ratio	600:1 (Typ)
	Viewing angle	Left and right: each 80°, upward: 80°, downward: 60°
	Backlight Unit	LED, edge-light
	Backlight lifetime	About 100,000hour
	Touch panel	4wire resistive touch screen
	Video input	analog RGB
External interface	Touch panel signal	USB
	Touch panel signal	RS-232C
	Power supply voltage	24 VDC (21.6 to 26.4 VDC)
Ratings	Current consumption	0.5A
Rutings	Insulation resistance	Between DC power supply and Touch Panel Monitor FG: 20 $\mbox{M}\Omega$ or higher (rated voltage 250 V)
	Ambient temperature range	Operating: 0 to 50°C, Storage: -20 to +65°C (with no icing or condensation)
	Ambient humidity range	Operating and Storage: 20 to 90 %RH (with no icing or condensation)
Operating	Ambient environment	No corrosive gas
environment	Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm (Max. acceleration 15 m/s²) 10 times for 8 minutes for each three direction
	Degree of protection	Panel mounting: IP65 on the front
Operation		Touch pen
	Mounting	Panel mounting, VESA mounting
Structure	Weight	Approx.2.6 kg
	Material	Front panel: PC/PBT, Front Sheet: PET, Rear case: SUS

Note: FH Series Sensor Controllers version 5.32 or higher is required.

#### **Monitor Cables**

Model	FH-VMDA (2 m)	FH-VUAB (2 m)	XW2Z-200PP-1 (2 m)			
Cable type	DVI-Analog Conversion Cable	USB Cable	RS-232C Cable			
Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm.	, 10 times for 8 minutes for each three direct	tion			
Ambient Temperature	Operating Condition: 0 to 50°C, Storage C	Operating Condition: 0 to 50°C, Storage Condition: -10 to 60°C (with no icing or condensation)				
Ambient Humidity	Operating Condition: 35 to 85%RH, Storage	Operating Condition: 35 to 85%RH, Storage Condition: 35 to 85%RH (with no icing or condensation)				
Ambient environment	No corrosive gases	No corrosive gases				
Material	Cable outer sheath, Connector: PVC  Cable outer sheath: PVC  Connector: ABS/Ni Plati					
Minimum bend radius	36 mm	25 mm	59 mm			
Weight	Approx.220 g	Approx.75 g	Approx.162 g			

#### **LCD Monitor**

Model	FZ-M08
Size	8.4 inches
Туре	Liquid crystal color TFT
Resolution	1,024 × 768 dots
Input signal	Analog RGB video input, 1 channel
Power supply voltage	21.6 to 26.4 VDC
Current consumption	Approx. 0.7 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 1.2 kg
Accessories	Instruction Sheet and 4 mounting brackets

# **EtherCAT Communications Specifications**

Item		Specifications
Communications standard		IEC61158 Type 12
Physical layer		100 BASE-TX (IEEE802.3)
Modulation		Base band
Baud rate		100 Mbps
Topology		Depends on the specifications of the EtherCAT master.
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)
Transmission Distance		Distance between nodes: 100 m or less
Node address setting		00 to 99
External connection terminals		RJ45 × 2 (shielded) IN: EtherCAT input data, OUT: EtherCAT output data
Send/receive PDO data sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *
	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *
Mailbox data size	Input	512 bytes
	Output	512 bytes
Mailbox		Emergency messages, SDO requests, and SDO information
Refreshing methods		I/O-synchronized refreshing (DC)

<sup>\*</sup> This depends on the upper limit of the master.

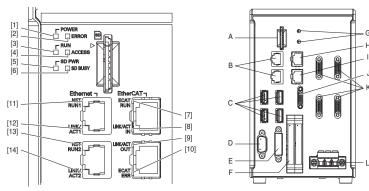
#### **Version Information**

FH Series and Programming Devices
Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

FH Series	Version of FH Series	Corresponding version of Sysmac Studio Standard Edition/Vision Edition
FH-5550 (-□) FH-5050 (-□) FH-2050 (-□)	Version 6.51 or higher	Supported by version 1.53 or higher.
	Version 6.40	Supported by version 1.43 or higher.
	Version 6.31	Supported by version 1.30 or higher.
	Version 6.21	Supported by version 1.26 or higher.
	Version 6.11	Supported by version 1.25 or higher.
	Version 5.72	Supported by version 1.18 or higher.
	Version 5.71	Supported by version 1.18 or higher.
	Version 5.60	Supported by version 1.15 or higher.
	Version 5.50	Supported by version 1.14.89 or higher.
	Version 5.30	Supported by version 1.10.80 or higher.
	Version 5.20	Supported by version 1.10 or higher.
	Version 5.10	Supported by version 1.07.43 or higher.
	Version 5.00	Supported by version 1.07 or higher. Not supported by version 1.06 or lower.

# **Components and Functions**

Sensor Controllers High-speed, Large-capacity Controller Standard Controller (4-camera type)

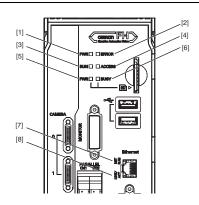


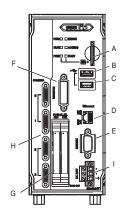
	Name	Description
[1]	POWER LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD POWER LED	Blinks while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Blinks while the SD memory card is accessed.
[7]	EtherCAT RUN LED	Lit while EtherCAT communications are usable.
[8]	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[9]	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[10]	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.
[11]	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.
[12]	EtherNet LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.
[13]	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.
[14]	EtherNet LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.

	Name	Description		
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.		
		Connect an EtherNet device.		
		FH-2050 Series/FH-5⊡50 Series		
В	EtherNet connector	Upper port: Ethernet port Lower port: Ethernet port, EtherNet/IP port, and PROFINET port are sharing use.		
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement operation. Otherwise measurement time may be affected or data may be destroyed.		
D	RS-232C connector	Connect an external device such as a programmable controller.		
Е	DVI-I connector	Connect a monitor.		
F	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.		
G	EtherCAT address setup volume	Used to set a node address (00 to 99) as an EtherCAT communication device.		
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.		
1	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.		
J	Encoder connector	Connect an encoder.		
K	Camera connector	Connect cameras.		
L	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the controller alone.		

<sup>\*</sup> Use the attachment power terminal connector (male) of FH-XCN series.
For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual (Z366).

# Lite Controllers (4-camera type)





	LED name	Description
[1]	PWR LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD PWR LED	Lit while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Lit when access to the SD memory card.
[7]	Ethernet NET RUN LED	Lit while Ethernet communications are usable.
[8]	Ethernet LINK/ACT LED	Blinks when connected with an Ethernet device, and blinks while performing communications.

	Connector name	Description	
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation Otherwise measurement time may be affected or data may be destroyed.	
В	USB 2.0 connector	Connects to USB 2.0. Do not insert or remove during loading or writing of measurement or data. The measurement time can be longer or data can be damaged.	
С	USB 3.0 connector	Connects to USB 3.0. Do not insert or remove during loading or writing of measurement or data. The measurement time can be longer or data can be damaged.  USB 3.0 has a high ability to supply the bus power.  Use the Sensor Controller by combining USB 3.0, faster transport can be realized.	
D	Ethernet connector	Connect an Ethernet device. Ethernet port, EtherNet/IP port, and PROFINET port are sharing use.	
Е	RS-232C connector	Connect an external device such as a programmable controller.	
F	DVI-I connector	Connect a monitor.	
G	Parallel connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor.	
Н	Camera connector	Connect a camera.	
ı	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the FH Sensor Controller alone.	

<sup>\*</sup> Use the attachment power terminal connector (male) of FH-XCN-L series.
For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual(Z366).

# **Processing Items**

Group	lcon	Processing Item		Corresponding Page in the Catalog
	à	Search	Used to identify the shapes and calculate the position of measurement objects.	
Î	600	Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.	
·	清	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.	
·	-	ECM Search	Used to search the similar part of model form input image. Detect the evaluation value and position.	
·	<b>\( \begin{array}{c} \\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ </b>	EC Circle Search	Extract circles using "round " shape information and get position, radius and quantity in high preciseness.	
	2	Shape Search II	Used to search the similar part of model from input image regardless of environmental changes. Detect the evaluation value and position.	
	ш ф <u>2</u> -2	Shape Search III	Robust detection of positions is possible at high-speed and with high precision incorporating environmental fluctuations, such as differences in individual shapes of the workpices, pose fluctuations, noise superimposition and shielding.	P12
·	-	EC Corner	This processing item measures a corner position (corner) of a workpiece.	
	*	Ec Cross	The center position of a crosshair shape is measured using the lines created by the edge information on each side of the crosshair.	
	<b>a</b>	Classification	Used when various kinds of products on the assembly line need to be sorted and identified.	
		Edge Position	Measure position of measurement objects according to the color change in measurement area.	
	<b>###</b>	Edge Pitch	Detect edges by color change in measure- ment area. Used for calculating number of pins of IC and connectors.	
	#	Scan Edge Position	Measure peak/bottom edge position of workpieces according to the color change in separated measurement area.	P12
	畫	Scan Edge Width	Measure max/min/average width of work- pieces according to the color change in separated measurement area.	
		Circular Scan Edge Position	Measure center axis, diameter and radius of circular workpieces.	P12
Measurement		Circular Scan Edge Width	Measure center axis, width and thickness of ring workpieces.	
		Intersection	Calculate approximate lines from the edge information on two sides of a square workpiece to measure the angle formed at the intersection of the two lines.	
	2	Color Data	Used for detecting presence and mixed varieties of products by using color average and deviation.	
		Gravity and Area	Used to measure area, center of gravity of workpices by extracting the color to be measured.	
		Labeling	Used to measure number, area and gravity of workpieces by extracting registered color.	
		Label Data	Selecting one region of extracted Label- ing, and get that measurement. Area and Gravity position can be got and judged.	
	M	Defect	Used for appearance measurement of plain-color measurement objects such as defects, stains and burrs.	
	M	Precise Defect	Check the defect on the object. Parameters for extraction defect can be set precisely.	
		Fine Matching	Difference can be detected by overlapping and comparing (matching) registered fine images with input images.	
	AB	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].	P15
	Date 08-02-1	Date Verification	Reading character string is verified with internal date.	
	A	Model Dictionary	Register character pattern as dictionary. The pattern is used in [Character Inspection].	
	DEE!	2DCode II *1	Recognize 2D code and display where the code quality is poor.	P15
		2DCode *2	Recognize 2D code and display where the code quality is poor.	
•		Barcode *3	Recognize barcode, verify and output decoded characters.	
İ	OCR	OCR	Recognize and read characters in images as character information.	P15
	OCR	OCR User Dictionary	Register dictionary data to use for OCR.	
		Dictionally	Used for calculating angle of inclination of	

Camera Image Input FH	Group	Icon		Processing Item	Page in the Catalog
Af FineMatching value and effects the difference between the input image and the non-defective produces and detects only defects.  Camera Image Input FIH Image In conditions to input images from cameras. And set up the production of input images from cameras, and set up the production of input images from cameras. And set up the production of input images from cameras and set up the production of input images from cameras. And set up the production of input images with different congruence of the production of input images with different congruence of input input images input from congruence of input images. Input images at user-defined timings and executes parallel measurement. Not input images at user-defined timings and executes parallel measurement for each image. Insert the Multi-rigger imaging processing item congruence in put images.  Position Compensation Defendence of the top of the flow.  Position Compensation Defendence of the congruence of the put images and executes parallel measurement for each image and executes parallel measurement for order to make them easier to be measured.  Position Support in the put images of the put images in the put images and ex				or for gaps or runoffs along the coating	
Camera Image   Input First   Camera Image   Input First   Camera Image   Input Horitage   Camera Image   Input Horitage   Camera Image   Input Horitage   Inp	Measurement			uct images and detects the difference be- tween the input image and the non-defective image. Allows for variations in non-defective	P6
Camera Image   pupil HDR		噢		the conditions to input images from camer-	
Input Image    Input Image				quiring several images with different con-	P10
Input Image    Stereo Image   Injut					
Input Image    Camera Switching again.   To switch the images used for measure-ment Image Switching again.   To switch the images used for measure-ment. Not input images from camera again.   The Multi-trigger Imaging processing item captures multiple images at user-defined the image of the post of the flow.   The Multi-trigger Imaging processing item captures multiple images at user-defined the images in the post of the flow.   The Multi-trigger Imaging processing item captures multiple images at user-defined the images in the post of the flow.   The Multi-trigger Imaging processing item captures multiple images at user-defined the images and executes parallel measure-image in the top of the processing item captures multiple images at user-defined the capture image in capture multiple images at user-defined the capture images of processing image by potential processing image.		""	Stereo Image	tion directions using a photometric stereo	
ment. Not input images from camera again.  The Multi-rigger Imaging processing lem captures multiple image at user-defined trings and executes parallel measurement mage. Insert the Multi-trigger lmaging to the top of the flow.  The Multi-rigger imaging processing item captures multiple images at user-defined trings and executes parallel measurement again.  Position Position Position Compensation Compensation Filtering Background Suppression Background Suppression Filtering Background Suppression Filtering Brightness Conect Filter Color Gray Filter Filter and Filtering Color images is converted into monochrome images to emasured.  Color Gray Filter Filter and Filtering Filtering Stripes Removal Filter II Filtering Fil	Input Image	D	Camera Switch	ment. Not input images from cameras	
Autit-trigger Imaging with the properties of the processing item to the pot of the flow the pot of the pot of the pot of the pot of the processing flem to the top of the processing which requires imaging for multiple times.    Position   Compensation   Used when positions are differed. Correct pressurement is performed by correcting position of input images.   Used for processing item to the top of the processing which requires imaging for multiple times.   Used for processing image input from the position of input images.   Used for processing image input from the flow measurement is performed by correcting position of input images.   Used for processing image input from the measurement is performed by correcting position of input images.   Used for processing image input from the measurement in performed by correcting position of input images.   Used for processing image is converted into monochrome images to emphasize specific color.   If the processing item and addition of the processing item and addition of the processing item and addition of the image of binary image.   Polar Transformation   Useful for OCR or pattern inspection printing of on circle.   Polar Transformation   Useful for OCR or pattern inspection printing of the processing item and addition   Polar Transformation   Useful for OCR or pattern inspection printing in order to make them easier to measurement image are compared and only the different pixels are existed and converted to an image.   Process the images acquired from cameration of the image when each stage or robot axis is controlled can be checked.   Polar Transformation   Processing item consolidates   Processing item   Pro				ment. Not input images from camera	
Multi-trigger Imaging Task Imag				captures multiple images at user-defined timings and executes parallel measure- ment for each image. Insert the Multi-trig-	P10
Filtering background Suppression in Justines Serven and remove gradual brightness change store to make them easier to be measured.    Background Suppression   To enhance contrast of images by extracting color in specified brightness. Track brightness change of entire screen and remove gradual brightness change such as uneven brightness change such as uneven brightness. Color Gray Filter   Stract Color Filter or convert color image is converted into monochrome images to emphasize specific color.    Extract Color Filter or convert color image is converted into monochrome images to emphasize specific color.    Anti Color Shading To remove the irregular color/pattern by uniformizing max. 2 specified colors. Stripes Removal Filter II or remove the irregular color/pattern by uniformizing max. 2 specified colors.    Stripes Removal Filter II or remove the irregular color/pattern by uniformizing max. 2 specified colors. Remove the background pattern of vertical, horizontal and diagonal stripes.    Polar Transformation Useful for OCR or pattern inspection printed on circle.   Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.   How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.   The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.   Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.				captures multiple images at user-defined timings and executes parallel measure- ment for each image. Insert this process- ing item to the top of the processing which	
Filtering cameras in order to make them easier to be measured.  Background Suppression in color in specified brightness.  Track brightness change of entire screen and remove gradual brightness change such as uneven brightness.  Color Gray Filter  Color Gray Filter  Extract Color Filter  Anti Color Shading To remove the irregular color/pattern by uniformizing max. 2 specified colors.  Stripes Removal Filter II Trapezoidal portional stripes.  Compensate image  Polar Transformation  Transformation Useful for OCR or pattern inspection printed on circle.  Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.  Rectify the ripezoidal deformed image.  How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.  The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing litem and adds extra functions.  Combine multiple image to create one big image.  Unit Macro  Unit Calculation Macro  Calculation Macro  Calculation Filter is for incurrence and only the different pixels are extracted and converted to an image.  Filter II This function is convenient when the user was in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing litems.  This function is convenient when the user was incompared and converted to an image.  Calculation formula or change the set value or system data of a processing item.  Line Regression Line Regression circle from plural measurement coordinate.  Line Regression Used for calculating regression circle from plural measurement coordinate.		=		measurement is performed by correcting	
Brightness Correct Filter  Brightness Correct Filter  Color Gray Filter  Color Gray Filter  Color image is converted into monochrome images to emphasize specific color.  Extract Color Filter  Anti Color Shading  Anti Color Stripes Removal Filter II  Polar Transformation  Filter II  Polar Transformation  Machine Simulator  Advanced filter  Advanced filter  Advanced filter  Advanced filter  Al Scratch Detect Filter "5  Al Scratch Detect Filter "5  Unit Calculation Macro  Calculation  Calculation  Calculation  Line Regression  Loor Cordor image to color extracted images to converted inage and remeasurement processing units.  Transformation  To remove the irregular color/pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Rectify the image by polar transformation. Useful for OCR or pattern inspection printed image.  Rectify the image by polar transformation.  Rectify the image by polar transformation.  Life filter II  Stripes.  Rectify the image by polar transformation.  Life filter II  Stripes.  Rectify the image and measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from camerasin order to make them easier to measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from camerasin order to make them easier to measurement into workf		M	Filtering	cameras in order to make them easier to	
Compensate image  Polar Transformation  Wachine Simulator  Subtraction  Advanced filter  Advanced filter  Advanced filter  Advanced filter  Advanced filter  Al Scratch Detect Filter *5  Line Regression  Unit Calculation Macro  Calculation reages converted into monochrome images to emphasize specific color.  Corvert color image to color extracted image or binary image.  Corvert color image to color extracted image or binary image.  Anti Color Shading  Stripes Removal Filter II  To remove the irregular color/pattern oby uniformizing max.2 specified colors.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Rectify the image by polar transformation.  Useful for OCR or pattern inspection printed on circle.  Rectify the trapezoidal deformed image.  How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.  The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.  Combine multiple image to create one big image.  Unit Macro  Unit Macro  Unit Macro  Calculation macro advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing items.  This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Line Regression  Used for calculating regression line from plural measurement coordinate.  Used for calculating regression in ine from plural measurement coordinate.					
Extract Color Filter images to emphasize specific color.  Extract Color Filter age or binary image.  Anti Color Shading by niformizing max.2 specified colors.  Stripes Removal Filter II Stripes.  Stripes Removal Filter II Stripes.  Polar Transformation Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.  Machine Simulator How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.  The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.  Al Scratch Detect Filter *5 Extracts defects in the set measurement area.  Unit Calculation Macro  Unit Macro  Calculation Extracts defects in the set measurement area.  Unit Calculation Macro be easily incorporated into workflow as Unit Macro processing item.  Used when using the judge results and measured values of Proctlem which are registered in processing item.  Used when using the judge results and measured values of Proctlem which are registered in processing item.  Line Regression Used for calculating regression line from plural measurement coordinate.  Extracts calculating regression line from plural measurement coordinate.  Extracts calculating regression circle from plural measurement coordinate.				screen and remove gradual brightness	
Filter age or binary image.  Anti Color Shading by uniformizing max.2 specified colors.  Stripes Removal Filter II Stripes Removal Filter II Stripes Removal Filter II Stripes Removal Filter II Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Rettify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.  How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.  The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.  Panorama Process the images acquired from camerals in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.  Combine multiple image to create one big image.  Al Scratch Detect Filter *5  Unit Macro  Unit Macro  Unit Calculation Macro  Calculation macro  Calculation formula or change the set value or system data of a processing item.  This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Line Regression  Used when using the judge results and measured values of Proctlem which are registered in processing uints.  Used for calculating regression line from plural measurement coordinate.  Line Regression plural measurement coordinate.			Color Gray Filter		
Shading by uniformizing max.2 specified colors.  Remove the background pattern of vertical, horizontal and diagonal stripes.  Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.  Rectify the trapezoidal deformed image.  Rectify the trapezoidal can be deformed image.  Process the image sac current on emage are compared and only the different pixels are extracted and converted to an image.  Process the image sac current image are compared and only the different pixels are extracted and converted to an image.  Process the image sacquired from cameras in order to make them easier to measurement as in order to make them easier to measurement as in order to make them easier to measurement in order to make them easier to measurement in order to make them easier to m					
Compensate image  Polar Transformation  Trapezoidal Correction  Machine Simulator  Machine Simulator  Machine Subtraction  Machine Subtraction  Polar Trapezoidal Correction  Machine Simulator  Machine Simulation Swould move on the security solicition or make theme astrage aroundand only the different pixels are extracted and converted to an image.  Processing litem and adds extra functions.  Combine multiple image to create one big image.  Extracts defects in the set measurement area.  Advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing item.  This function is convenient when the user wasts to calculate a value using an original calculation formula or change the					
Transformation Transformation Transformation Trapezoidal Correction  Machine Simulator  Machine Simulator  How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.  The registered model image and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.  Combine multiple image to create one big image.  Al Scratch Detect Filter *5  Unit Macro  Unit Macro  Unit Calculation Macro  Calculation  Calculation  Calculation  Calculation  Used when using the judge results and measurement are gistered in processing item.  Used for calculating regression line from plural measurement coordinate.  Extracts defects in the set measurement area.  Advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing items.  This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Used when using the judge results and measured values of Proctlem which are registered in processing units.  Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.	Compensate			vertical, horizontal and diagonal	
Machine Simulator	image	ABC		Useful for OCR or pattern inspection print-	
the image when each stage or robot axis is controlled can be checked.  The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measurement image conversion filtering into one processing item and adds extra functions.  Panorama Combine multiple image to create one big image.  Extracts defects in the set measurement area.  Advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing items.  Unit Calculation Macro advanced arithmetic processing an be easily incorporated into workflow as Unit Macro processing items.  Unit Calculation Wacro processing tems.  Used when using the judge results and measured values of Proclem which are registered in processing item.  Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.					
Image Subtraction  Image are compared and only the different pixels are extracted and converted to an image.  Process the images acquired from cameras in order to make them easier to measurement image conversion filtering into one processing item and adds extra functions.  Panorama  Panorama  Combine multiple image to create one big image.  Extracts defects in the set measurement area.  Advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing items.  Unit Calculation Macro processing items.  This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Support measurement  Calculation  Line Regression  Line Regression  Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.		-		the image when each stage or robot axis is	
as in order to make them easier to measurement and adds extra functions.  Panorama  Panorama  Combine multiple image to create one big image.  Al Scratch Detect Filter *5  Unit Macro  Unit Macro  Unit Calculation Macro  Calculation  Calculation  Calculation  Calculation  Used when using the judge results and measured values of Proctem which are registered in processing tiems.  Used for calculating regression line from plural measurement coordinate.  Line Regression  Lise Precise  Used for calculating corresponding to trape-				measurement image are compared and only the different pixels are	
Al Scratch Detect Filter *5  Unit Macro  Unit Calculation Macro  Calculation  Calculation  Line Regression			Advanced filter	as in order to make them easier to mea- sure. This processing item consolidates existing image conversion filtering into one	
Unit Macro  Unit Macro  Unit Macro  Unit Calculation Final Calculation formula or change the set value or system data of a processing item.  Used when using the judge results and measured values of Procitem which are registered in processing units.  Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.			Panorama		
Unit Macro easily incorporated into workflow as Unit Macro processing items.  This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Support Calculation Used when using the judge results and measured values of Procitem which are registered in processing units.  Line Regression Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from Regression plural measurement coordinate.  Precise Used for calibration corresponding to trape-					P4
Unit Calculation wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.  Support Calculation Used when using the judge results and measured values of Proclem which are registered in processing units.  Line Regression Used for calculating regression line from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.  Used for calculating regression circle from plural measurement coordinate.		<b>-</b>	Unit Macro	easily incorporated into workflow as Unit	
Calculation measured values of Procitem which are registered in processing units.  Line Regression Used for calculating regression line from plural measurement coordinate.  Circle Circle Regression plural measurement coordinate.  Line Regression Used for calculating regression circle from plural measurement coordinate.  Line Regression Used for calibration corresponding to trape-		<b>*</b>		wants to calculate a value using an original calculation formula or change the set val-	
Used for calculating regression   Divided from Planta   Used for calculating regression circle from Regression   Divided from Planta   Divided from Plan			Calculation	measured values of Procitem which are	
Regression plural measurement coordinate.  Precise Used for calibration corresponding to trape-		+	Line Regression		
		O			
Zoldal distortion and lens distortion.			Precise Calibration	Used for calibration corresponding to trapezoidal distortion and lens distortion.	

Group	Icon	Processing Item		Corresponding Page in the Catalog
	User	User Data	Used for setting of the data that can be used as common constants and variables in scene group data.	
		Set Unit Data	Used to change the ProcItem data (setting parameters, etc.) that has been set up in a scene.	
		Get Unit Data	Used to get one data (measured results, setting parameters, etc.) of ProcItem that has been set up in a scene.	
		Set Unit Figure	Used for re-setting the figure data (model, measurement area ) registered in an unit.	
	-	Get Unit Figure	Used for get the figure data (model, measurement area ) registered in an unit.	
		Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.	
	<b>=</b>	Image Logging	Used for saving the measurement images to the memory and USB memory.	
	<b>□</b> →	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.	
	①\$	Data Logging	Used for saving the measurement data to the memory and USB memory.	
	<b>\$</b>	Elapsed Time	Used for calculating the elapsed time since the measurement trigger input.	
	I	Wait	Processing is stopped only at the set time. The standby time is set by the unit of [ms].	
	3	Focus	Focus setting is supported.	
	<b>**</b>	Iris	Focus and aperture setting is supported.	
	000	Parallelize	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of processing to be performed in parallel.	
	1000	Parallelize Task	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed immediately before processing to be performed in parallel between Parallelize and Parallelize End.	
Support neasure-		Statistics	Used when you need to calculate an average of multiple measurement results.	
nent	•	Reference Calib Data	Calibration data and distortion compensa- tion data held under other processing items can be referenced.	
		Position Data Calculation	The specified position angle is calculated from the measured positions.	
	<u>+</u> /	Stage Data	Sets and stores data related to stages.	P13
	70	Robot Data	Sets and stores data related to robots.	
		Vision Master Calibration	This processing item automatically calculates the entire axis movement amount of the control equipment necessary for calibration.	
	<b>*</b>	PLC Master Calibration	Calibration data is created using a communication command from PLC.	
	ز!	Convert Position Data	The position angle after the specified axis movement is calculated.	
		Movement Single Position	The axis movement that is required to match the measured position angle to the reference position angle is calculated.	
	###/	Movement Multi Points	The axis movements that are required to match the measured position angles to the corresponding reference position angles are calculated.	
	+	Detection Point	Obtains position/angle information by re- ferring to the coordinate values measured with the Measurement Processing Unit.	
	+===	Manual Position Setting	Used to change the measurement coordinates X and Y of the measurement processing unit.	
	- · ·	Camera Calibration	By setting the camera calibration, the measurement result can be converted and output as actual dimensions.	
	<b>#</b>	Data Save	The set data can be saved in the controller main unit or as scene data. The data is held even after the FH/FZ power is turned off.	
	2	Conveyor Calibration	Conveyor Calibration is used to calibrate camera, conveyor, and robots for conveyor tracking application.	
		Scene	The specified scene is copied to the current scene.	
	@	System Information	Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.	

Group	Icon			Corresponding Page in the Catalog
	-	Conditional Branch	Used where more than two kinds of products on the production line need to detected separately.	
	# (O)	End	This ProcItem must be set up as the last processing unit of a branch.	
		DI Branch	Same as ProcItem "Branch". But you can change the targets of conditional branching via external inputs.	
	100	Control Flow Normal	Set the measurement flow processing into the wait state in which the specific no-pro- tocol command can be executed.	
	100	Control Flow PLC Link	Set the measurement flow processing into the wait state in which the specific PLC Link command can be executed.	
		Control Flow Parallel	Set the measurement flow processing into the wait state in which the specific parallel command can be executed.	
		Control Flow Fieldbus	Set the measurement flow processing into the wait state in which the specific Field- bus command can be executed.	
Dranah	SMITCH	Selective Branch	Easily branch to multiple destinations.	
Branch	h	Conditional Execution (If)	The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.	
	h	Conditional Execution (Else)	Insert between the Conditional Execution (If) processing item and End If processing item. The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.	
	C	Loop	The set processes are repeated until the loop count reaches the specified number, and then the next process starts.	
	ţ	Loop Suspension	Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reaches the specified number.	
	¥	Select Execution (Select)	Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.	
	th.	Select Execution (Case)	Used to make a judgment. The measure- ment flow is divided according to the com- parison result obtained using the conditions given by expressions.	
	21 32 33 41.4	Result Output (I/O)	Output data to the external devices such as a programmable controller or a PC via PLC Link, Parallel interface, Fieldbus interface (EtherCAT, EtherNet/IP (other than message communication), PROF-INET).	
	123,A8C	Result Output (Message)	Output data to the external devices such as a programmable controller or a PC with non-procedure mode via the serial interface or EtherNet/IP (message communication). This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.	
Output result		Data Output	Used when you need to output data to the external devices such as PLC or PC via serial ports.	
		Parallel Data Output	Used when you need to output data to the external devices such as PLC or PC via parallel ports.	
	0K6	Parallel Judgement Output	Used when you need to output judgement results to the external devices such as PLC or PC via parallel ports.	
		Fieldbus Data Output	Outputs data to an external device, such as a Programmable Controller, through a fieldbus interface.	
	ОК	Result Display	Used for displaying the texts or the figures in the camera image.	
		Display Image File	Display selected image file.	
Display result	NG	Display Last NG Image	Display the last NG images.	
		Conveyor Panorama Display	Display images of the tracking area as a panoramic image.	
		Display Image Hold	Processing item to retain images, including measurement results.	

<sup>\*1 2</sup>D Codes that can be read : Data Matrix (ECC200)
\*2 2D Codes that can be read : Data Matrix (ECC200), QR Code
\*3 Bar Codes that can be read : JAN/EAN/UPC (including add-on codes), Code 39, Codabar (NW-7), ITF (Interleaved 2 of 5), Code 93, Code 128, GS1-128, GS1 DataBar (RSS-14 / RSS Limited / RSS Expanded), Pharmacode
\*4 Available on the following controllers:

FH-5□50/2050 Series (version 6.40 or later)
FH-L551-□□ (Use in conjunction with 0.3 or 0.4 million-pixel cameras.)

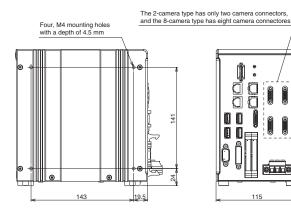
\*5 Available on the FH-5□50-series Controller (version 6.40 or later). Optional FH-UMAI1 Scratch Detect Al Software Installer is required.

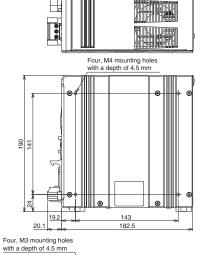
**Dimensions** (Unit: mm)

#### **Sensor Controllers**

High-speed, Large-capacity Controllers/Standard Controllers

FH-5550/-5550-10/-5550-20 FH-5050/-5050-10/-5050-20 FH-2050/-2050-10/-2050-20

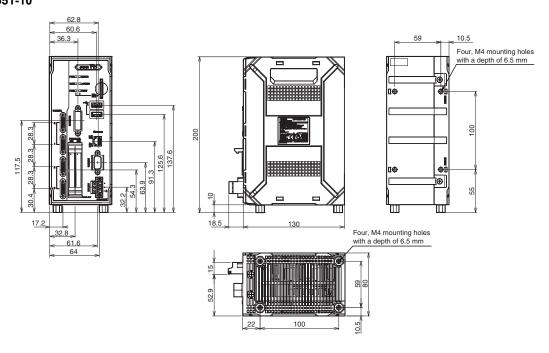






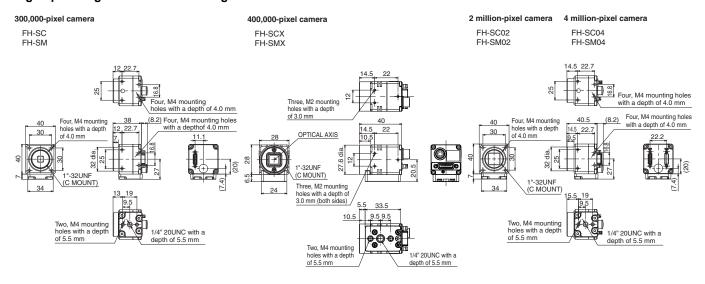
th a depth of 4.5 mm

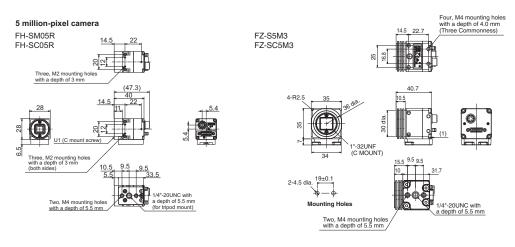
#### Lite Controllers FH-L551/-L551-10

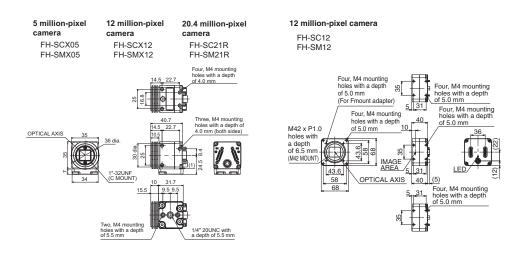


#### **Cameras**

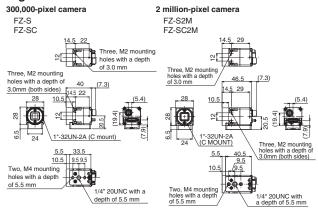
#### High-speed Digital CMOS Camera/Digital CMOS Camera





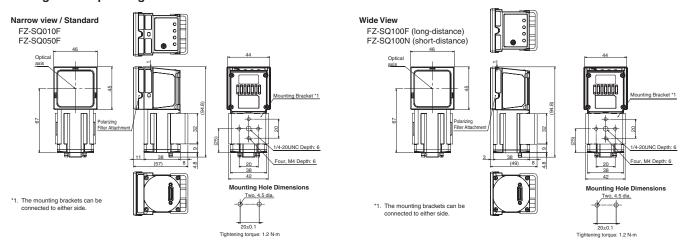


#### **Digital CCD/CMOS Cameras**



#### **Small digital CCD cameras** Camera head Camera amplifier Flat camera Can be used for both flat cameras and pen-shaped cameras Pen-shaped camera FZ-SP FZ-SPC FZ-SF FZ-SFC Two-4.3 dia Four, M1.7 mounting holes with a depth of 1.5 mm Three, M2 mounting holes with a depth of 3.0 mm 33 Eight, M1.7 mounting hole with a depth of 1.5 mm 16 pin round connector 12.7 9.6 7.5 20 pth of 3.0 mm Two, M3 mounting holes with a depth of 4 mm 12.5 dia. 1/4" 20UNC with a depth of 5.5 mm

#### **Intelligent Compact Digital CMOS Cameras**



#### **Cables**

#### **Camera Cable** Camera Cable Bend resistant Camera Cable FZ-VS3 FZ-VSB3 (40) (100) (40) (100) (11) rectangular connector Super Bend resistant Camera Cable FZ-VSBX (42) (40) (25) (100) (40) (25) **I** • 26-pin rectangular connector Right-angle Camera Cable Bend resistant Right-angle Camera Cable FZ-VSL3 FZ-VSLB3 (30) L (\*1) (100) (100) 26-pin 26-pin rectangular connecto rectangular connector æ Long-distance Camera Cable Long-distance Right-angle Camera Cable FZ-VS4 FZ-VSL4 (100) ₩ |• | 26-pin 26-pin rectangular connector \*1. Cable is available in 2m/3m/5m/10m. \*2. Each camera cables has polarity. Please ensure that the name plate side of the cable is connected to the controller. \*3. Cable is available in 5m/10m. \*4. Cable is available in 15m. (12)

# Camera Cable Extension Unit FZ-VSJ

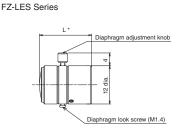
POWER LED

#### Extension Tubes for Small Camera

# FZ-LESR 3 5 Extension tubes 5 mm Extension tubes 10 mm

Extension tubes 15 mn

# Lens for Small Camera

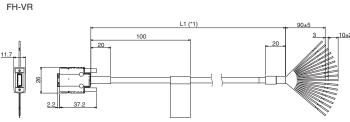


\* Overall length is available in 16.4mm/19.7mm/23.1mm/25.5mm.

# Encoder Cable

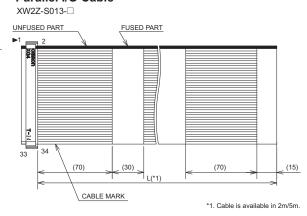
Camera Cable Con (Controller side)

Camera Cable Connector (Camera side)



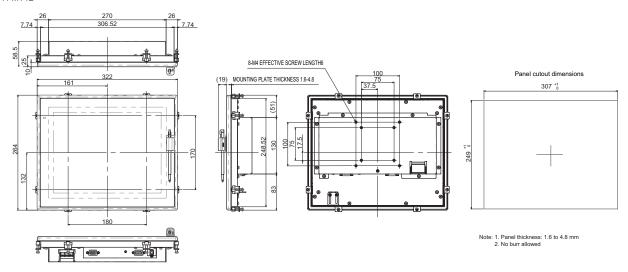
\*1. Cable is available in 1.5 m.

#### Parallel I/O Cable



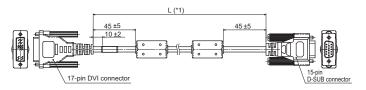
#### **Touch Panel Monitor**

FH-MT12



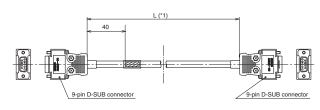
#### **DVI-Analog Conversion Cable for Touch Panel Monitor/LCD Monitor**

FH-VMDA



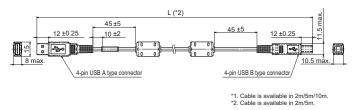
#### **RS-232C Cable for Touch Panel Monitor**

XW2Z-□□□PP-1



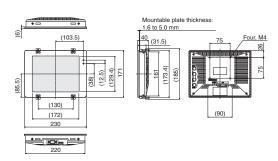
#### **USB Cable for Touch Panel Monitor**

FH-VUAB



#### **LCD** Monitor

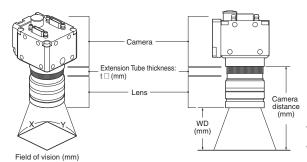
FZ-M08



# **Optical Chart**

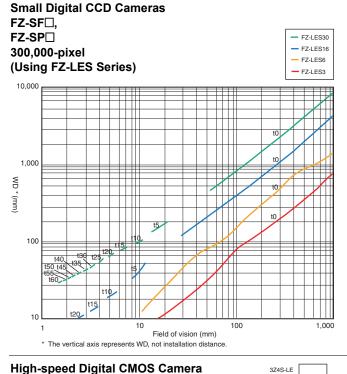
#### **Meaning of Optical Chart**

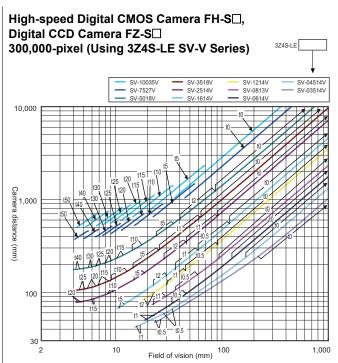
The X axis of the optical chart shows the field of vision (mm) (\*1), and the Y axis of the optical chart shows the camera installation distance (mm) (\*2).

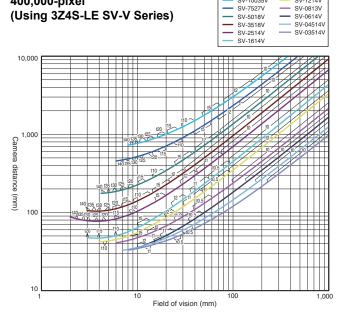


- \*1. The lengths of the fields of vision given in the optical charts are the lengths of the Y axis
- \*2. The vertical axis represents WD for small cameras.

#### Standard Lenses

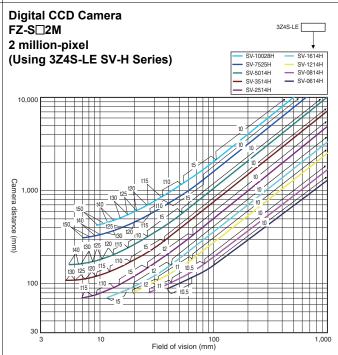






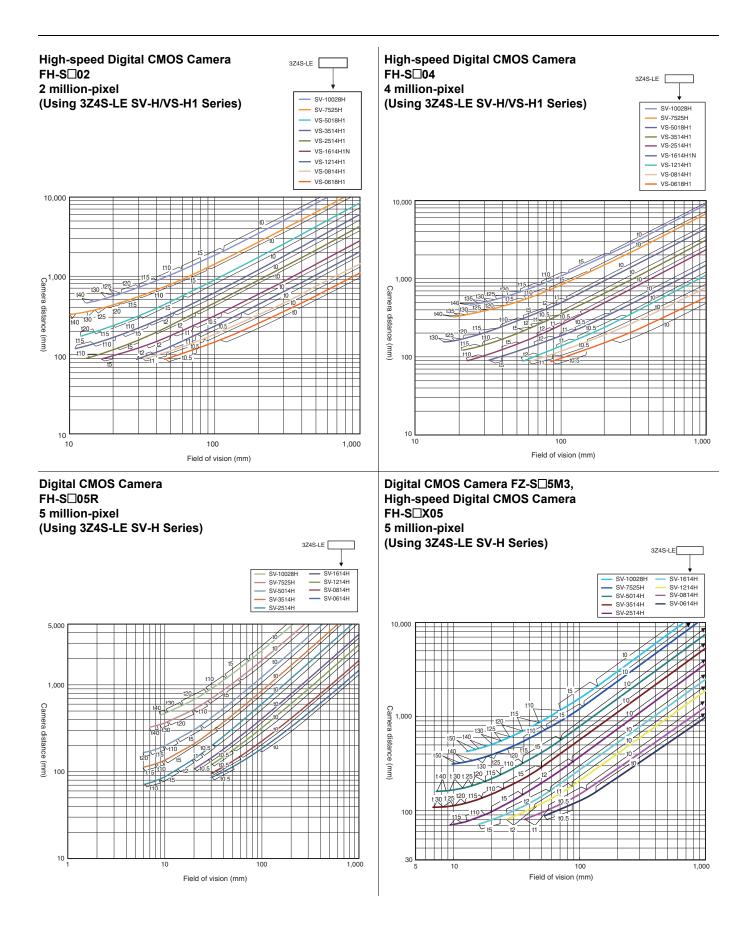
SV-10035V

SV-1214V

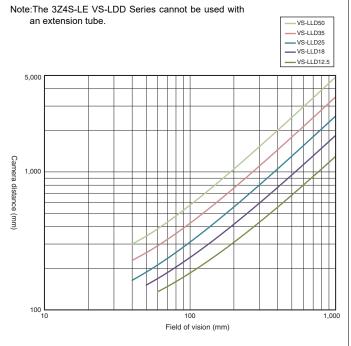


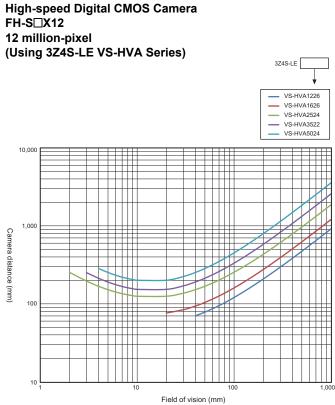
FH-S□X

400,000-pixel

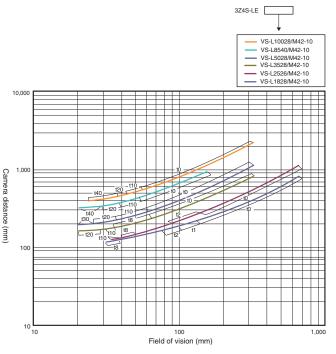




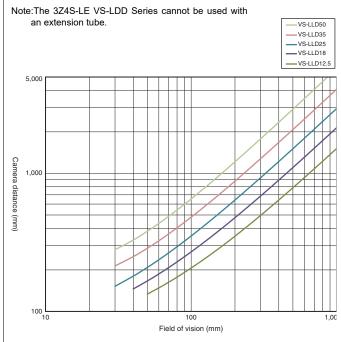


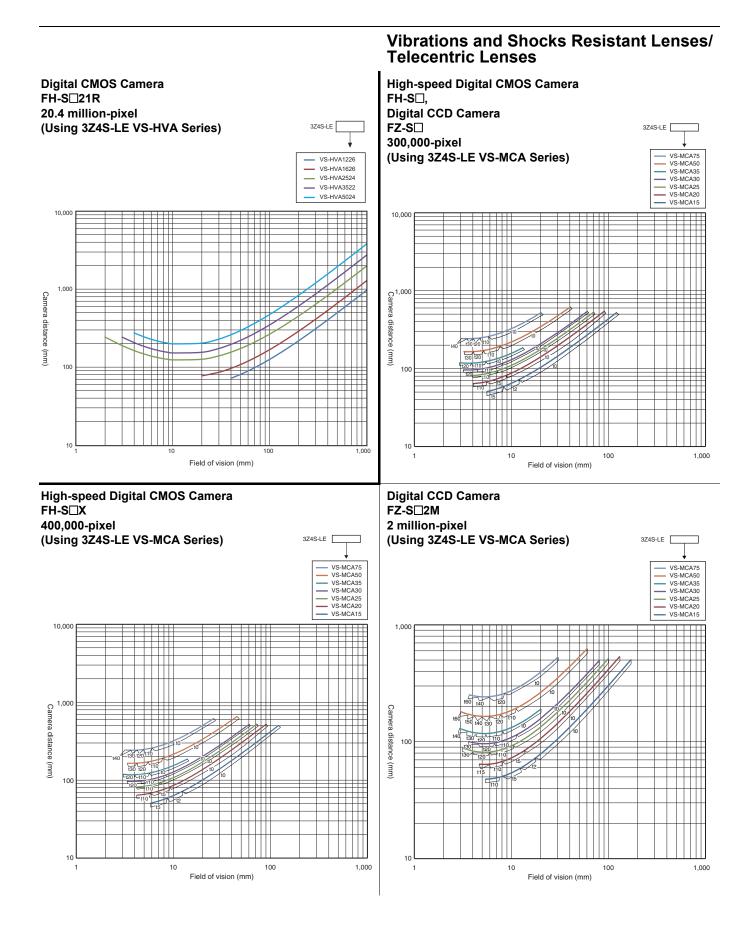


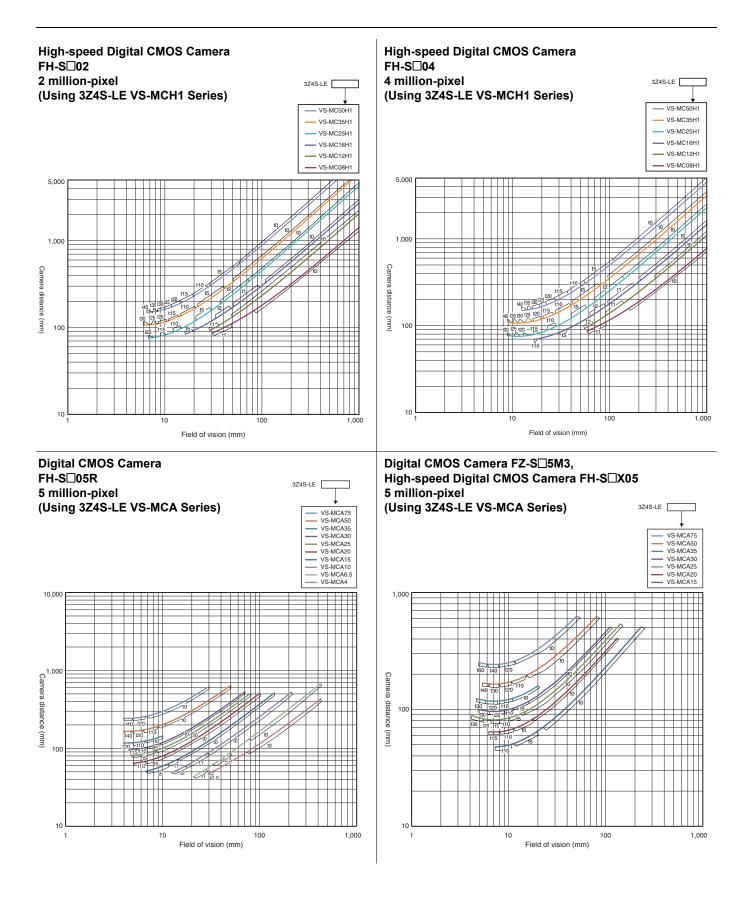
High-speed Digital CMOS Camera FH-S□12 12 million-pixel (Using 3Z4S-LE VS-L/M42-10 Series)

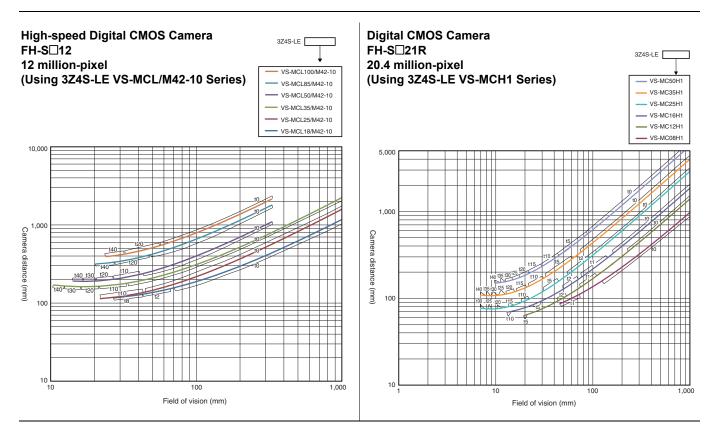


Digital CMOS Camera FH-S□21R 20.4 million-pixel (Using 3Z4S-LE VS-LLD Series)









## **Related Manuals**

Man.No.	Model number	Manual
Z365	FH/FHV7	Vision System FH/FHV7 Series User's Manual
Z341	FH/FHV7	Vision System FH/FHV7 series Processing Item Function Reference Manual
Z342	FH/FHV7	Vision System FH/FHV7 Series User's Manual for Communications Settings
Z343	FH/FHV7	Vision System FH/FHV7 Series Operation Manual for Sysmac Studio
Z366	FH	Vision System FH series Hardware Setup Manual
Z367	FH	Vision System FH series Macro Customize Functions Programming Manual
Z437	FH-UMAI	FH Application Software FH-UMAI Processing Item Function Reference Manual
Z438	FH-UMAI	FH Application Software FH-UMAI Version Update Tool Operating Manual

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