SIEMENS

Data sheet

3RK1308-0DD00-0CP0



Failsafe reversing starter High Feature; Electronic switching; Electronic overload protection up to 4 kW / 400 V; Adjustment range 2.8 .. 9 A; PROFIenergy; Option: 3DI/LC module

product brand name	SIMATIC				
product category	Motor starter				
product designation	Reversing starter				
product type designation	ET 200SP				
General technical data					
equipment variant according to IEC 60947-4-2	3				
product function	Fail-safe reversing starter				
 on-site operation 	Yes				
 intrinsic device protection 	Yes				
 remote firmware update 	Yes				
 for power supply reverse polarity protection 	Yes				
insulation voltage rated value	500 V				
degree of pollution	2				
overvoltage category	III				
surge voltage resistance rated value	6 kV				
maximum permissible voltage for protective separation					
 between main and auxiliary circuit 	500 V				
shock resistance	6g / 11 ms				
vibration resistance	15 mm to 6 Hz; 2g to 500 Hz				
operating frequency maximum	1 1/s				
mechanical service life (operating cycles) of the main contacts typical	30 000 000				
type of assignment	1				
utilization category					
 according to IEC 60947-4-2 	AC-53a: 9 A: (8-0,7: 70-32)				
reference code according to IEC 81346-2	Q				
Substance Prohibitance (Date)	04/15/2016				
SVHC substance name	Blei - 7439-92-1 Bleimonoxid (Bleioxid) - 1317-36-8 4,4'-isopropylidendiphenol (Bisphenol A, - 80-05-7 2,2',6,6'-Tetrabrom-4,4'-isopropylidendi - 79-94-7				
product function					
direct start	Yes				
reverse starting	Yes				
product component motor brake output	No				
product function short circuit protection	Yes				
design of short-circuit protection	fuse				
maximum short-circuit current breaking capacity (Icu)					
• at 400 V rated value	55 kA				
• at 500 V rated value	55 kA				
 at 500 V according to UL 60947 rated value 	100 kA				

maximum short-circuit current breaking capacity (Icu) in the IT network					
at 400 V rated value	55 kA				
	55 kA				
• at 500 V rated value	55 KA				
Electromagnetic compatibility					
EMC emitted interference according to IEC 60947-1	class A				
EMC immunity according to IEC 60947-1	Class A				
conducted interference					
 due to burst according to IEC 61000-4-4 	3 kV				
• due to conductor-earth surge according to IEC 61000-4-5	4 kV				
 due to conductor-conductor surge according to IEC 61000-4-5 	2 kV				
 due to high-frequency radiation according to IEC 61000- 4-6 	Class A				
field-based interference according to IEC 61000-4-3	20 V/m				
electrostatic discharge according to IEC 61000-4-2	8 kV air discharge				
conducted HF interference emissions according to	Class A for industrial environment				
CISPR11					
field-bound HF interference emission according to CISPR11	Class A for industrial environment				
Safety related data					
safety device type according to IEC 61508-2	Туре В				
safe state	Load circuit open				
B10d value	2 200 000				
Safety Integrity Level (SIL) according to IEC 61508	3				
performance level (PL) according to EN ISO 13849-1	е				
category according to EN ISO 13849-1	4				
stop category according to EN 60204-1	0				
diagnostics test interval by internal test function maximum	600 s				
PFH according to IEC 61508 relating to SIL	3.6E-9 1/h				
PFDavg with low demand rate according to IEC 61508	4.1E-7				
hardware fault tolerance according to IEC 61508	1				
protection class IP on the front according to IEC 60529	IP20				
touch protection on the front according to IEC 60529	finger-safe				
Main circuit	tinger-sate				
	3				
Main circuit number of poles for main current circuit design of the switching contact	3 Hybrid				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release	3 Hybrid 2.8 9 A				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%]	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 %				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 %				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 %				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 %				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 9 A				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 5 % 9 A 90 A				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 9 A				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 9 A 90 A 1.5 4 KW				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operational current at AC at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module 1				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating lower for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating lower for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module 1 Type 1 in accordance with EN 61131-2				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input • at DC rated value	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module 1 Type 1 in accordance with EN 61131-2 24 V				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input • at DC rated value • with signal <0> at DC	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module 1 Type 1 in accordance with EN 61131-2 24 V 0 5 V				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating prequency at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 5 % 9 A 90 A 1.5 4 kW				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC input current at digital input for signal <1> typical	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 9 A 90 A 1.5 4 kW 5 4 via 3DI/LC module 1 Type 1 in accordance with EN 61131-2 24 V 0 5 V				
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency relative positive tolerance of the operating frequency relative negative tolerance of the operating frequency operating prequency at 400 V rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs number of digital inputs • note • safety-related type of input characteristic input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC	3 Hybrid 2.8 9 A 50 %; from smallest adjustable rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 5 % 5 % 5 % 5 % 9 A 90 A 1.5 4 kW				

supply voltage 1 at DC rated value					
minimum permissible	20.4 V				
maximum permissible	28.8 V				
supply voltage at DC rated value	24 V				
consumed current for rated value of supply voltage					
 in standby mode of operation 	95 mA				
 during operation 	160 mA				
 at switching on of motor 	250 mA				
power loss [W] for rated value of supply voltage					
 in switching state OFF with bypass circuit 	2.3 W				
 in switching state ON with bypass circuit 	3.8 W				
inrush current peak at 24 V	25 A; Observe the manual for group configuration				
duration of inrush current peak at 24 V	0.145 ms				
Response times					
ON-delay time	35 ms				
· · · · · · · · · · · · · · · · · · ·	35 50 ms				
OFF-delay time	55 50 IIIS				
OFF-delay time with safety-related request	FF				
when switched off via control inputs maximum	55 ms				
when switched off via supply voltage maximum	120 ms				
Power Electronics					
operational current					
• at 40 °C rated value	9 A				
• at 50 °C rated value	9 A				
• at 55 °C rated value	9 A				
• at 60 °C rated value	7 A				
Installation/ mounting/ dimensions					
mounting position	Vertical, horizontal (observe derating)				
fastening method	pluggable in BaseUnit				
height	142 mm				
width	30 mm				
depth	150 mm				
required spacing with side-by-side mounting					
upwards	50 mm				
• downwards	50 mm				
downwards Ambient conditions	50 mm				
	4 000 m For derating one manual				
installation altitude at height above sea level maximum	4 000 m; For derating see manual				
ambient temperature					
during operation	-25 +60 °C; For derating see manual				
during storage	-40 +70 °C				
during transport	-40 +70 °C				
environmental category during operation according to IEC	3K6 (no formation of ice, no condensation), 3C3 (no salt mist), 3S2 (sand must				
60721	not get into the devices)				
relative humidity during operation	10 95 %				
air pressure according to SN 31205	900 1 060 hPa				
Communication/ Protocol					
protocol is supported					
PROFIBUS DP protocol	Yes				
PROFINET protocol	Yes				
product function bus communication	Yes				
protocol is supported AS-Interface protocol	No				
product function					
 supports PROFlenergy measured values 	Yes				
 supports PROFlenergy shutdown 	Yes				
address space memory of address range					
of the inputs	4 byte				
of the outputs	2 byte				
· · · · · · · · · · · · · · · · · · ·					
type of electrical connection of the communication interface Connections/ Terminals	Plug contact to Base Unit				
type of electrical connection					
	Pluggable module - accessory Plug contact to Base Unit				

type of electrical con	nection						
 for main energy 	infeed		Plug contact to Base Unit				
for load-side outgoing feeder		Plug conta	act to Base Unit				
 for supply voltage 	ge line-side		Plug conta	act to Base Unit			
wire length for motor unshielded maximum		200 m					
JL/CSA ratings							
full-load current (FLA) value	full-load current (FLA) for 3-phase AC motor at 480 V rated		9 A				
yielded mechanical p							
 for single-phase 	AC motor						
— at 110/120 V rated value		0.33 hp					
— at 230 V rated value		1 hp					
• for 3-phase AC motor							
— at 200/208	V rated value		2 hp				
— at 220/230	V rated value		2 hp				
— at 460/480	V rated value		5 hp				
operating voltage at AC rated value	C at 60 Hz according to CS	A and UL	480 V				
Certificates/ approvals							
General Product App	proval					EMC	
() E	<u>Confirmation</u>			(ال س	EHC	RCM	
For use in hazard- ous locations	Functional Safety/Safety of Ma- chinery	Declaration of	Conformity		Test Certificates	Marine / Shipping	
K ATEX	<u>Type Examination Cer-</u> <u>tificate</u>	CE EG-Konf.		UK CA	<u>Type Test Certific-</u> ates/Test Report	ABS	
Marine / Shipping			ot	her		Dangerous Good	
	ĴÅ	Lloyd's Register		Confirmation	00000	Transport Information	
BUREAU VERITAS	DNV	Uts			Profibus		
urther information							
	to exit the Russian marl		wn-russian-	business			
	on the renewal of the cur						
Please contact your loo	cal Siemens office on the s	tatus of validity of	the EAC ce	rtification if you inter	nd to import or offer to sup	ply these products to an	
Information on the pa	other than the sanctioned E	LAEU member sta	iles Russia (n delarus).			
	/.siemens.com/cs/ww/en/vi	<u>ew/109813875</u>					
	vnloadcenter (Catalogs, E	Brochures,)					
https://www.siemens.co Industry Mall (Online	ordering system)						
https://mall.industry.sie Cax online generator	emens.com/mall/en/en/Cata	alog/product?mlfb:	<u>=3KK1308-0</u>	<u>0420-00001</u>			
	on.siemens.com/WW/CAX	order/default.aspx	<u>(?lang=en&r</u>	nlfb=3RK1308-0DD	<u>00-0CP0</u>		
Service&Support (Ma	anuals, Certificates, Char	acteristics, FAQs	s,)				
	/.siemens.com/cs/ww/en/p						
Image database (prod	duct images, 2D dimensional dimens	on drawings, 3D	models, dev	∕ <mark>ice circuit diagra</mark> n <u>0-0CP0⟨=en</u>	ns, EPLAN macros,)		

